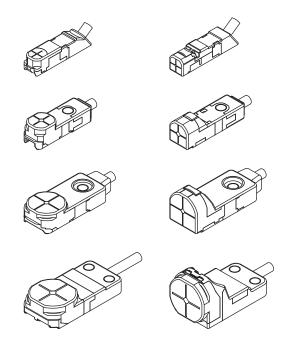
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Amplifier Built-in Rectangular-shaped Inductive Proximity Sensor

GX-F/H Series USER'S MANUAL



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1. Cautions

! WARNING

- Never use this product as a sensing device for personnel protection.
- In case of using devices for personnel protection, use products which meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.
- This product has been developed / produced for industrial use only.
- Make sure to check the wiring as wrong wiring will damage or burn the product.
- Make sure to carry out wiring in the power supply off condition.
- Take care that wrong wiring will damage the sensor.
- Verify that the supply voltage variation is within the rating.
- If power is supplied from a commercial switching regulator, ensure that the frame ground (F.G.) terminal of the power supply is connected to an actual ground.
- In case noise generating equipment (switching regulator, inverter motor, etc.) is used in the vicinity of this product, connect the frame ground (F.G.) terminal of the equipment to an actual ground.
- Do not run the wires together with high-voltage lines or power lines, or put them in the same raceway. This can cause malfunction due to induction.
- Do not use during the initial transient time (0.5 sec.) after the power supply is switched ON.
- Extension up to total 100m is possible with a 0.3mm², or more of conductor cross-section area cable.
- Make sure that stress by forcible bend or pulling is not applied to the sensor cable joint.
- This product is suitable for indoor use only.
- Do not use this sensor in places having excessive vapor, dust, etc., or where it may come in contact with corrosive gas, etc.
- Take care that the sensor does not come in contact with oil, grease, organic solvents such as thinner, etc., strong acid, or alkaline.
- This product cannot be used in an environment containing inflammable or explosive gasses.
- Never disassemble or modify the product.

2. Part Description

Front sensing GX-F6

Operation indicator (Orange)
Lights up when the output is ON.

Top sensing GX-H6□

Operation indicator (Orange)
Lights up when the output is ON.

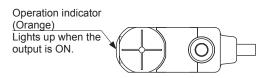
Front sensing GX-F8

Operation indicator (Orange)
Lights up when the output is ON.

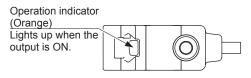
Top sensing GX-H8□

Operation indicator (Orange)
Lights up when the output is ON.

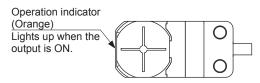
Front sensing GX-F12



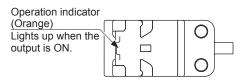
Top sensing GX-H12



Front sensing GX-F15 / GX-FL15



Top sensing GX-H15 / GX-HL15



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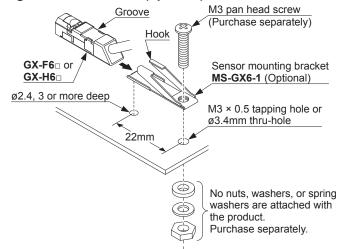
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3. Mounting

3-1 Mounting GX-F6□ and GX-H6□

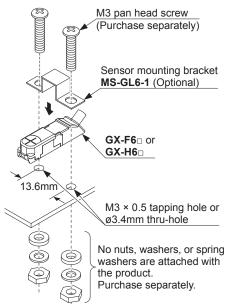
<In case of using sensor mounting bracket MS-GX6-1 (optional)>

- Insert the GX-F6 and GX-H6 into the sensor mounting bracket MS-GX6-1 as follows.
- Push the sensor until the hook of the sensor mounting bracket MS-GX6-1 catches the groove of the sensor.
- Mount the sensor mounting bracket MS-GX6-1 with a M3 pan head screw.



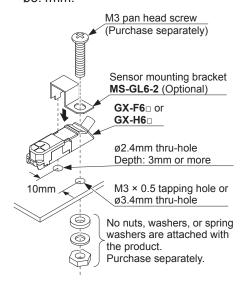
/In case of using sensor mounting∖ ∖bracket MS-GL6-1 (optional)

 To mount the sensor with a nut, the mounting hole diameter should be ø3.4mm.



In case of using sensor mounting bracket MS-GL6-2 (optional)

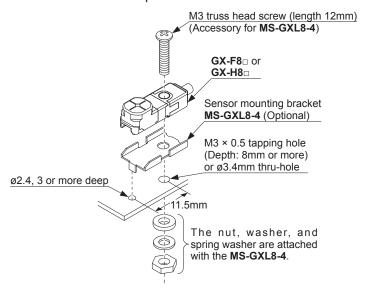
 To mount the sensor with a nut, the mounting hole diameter should be ø3.4mm.

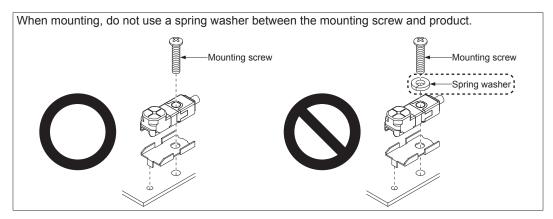


3-2 Mounting GX-F8□ and GX-H8□

<In case of using sensor mounting bracket MS-GXL8-4 (optional)>

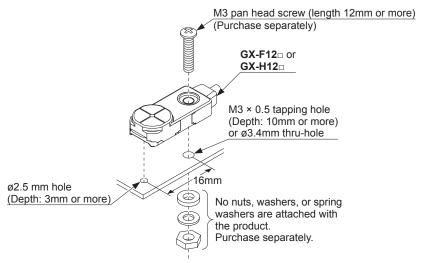
- Make sure to use a M3 truss head screw (length: 12mm) (accessory). The tightening torque should be 0.7N·m or less.
- To mount the sensor with a nut, the mouting hole diameter should be ø3.4mm.
- Do not use a fl at head screw or a pan head screw.

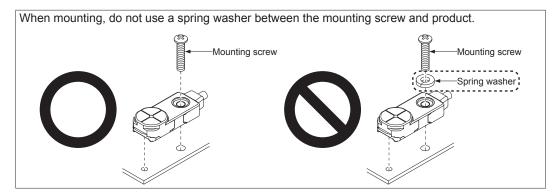




3-3 Mounting GX-F12□ and GX-H12□

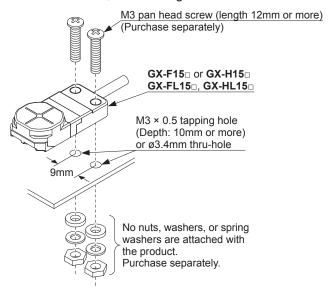
- The tightening torque should be 0.7N·m or less.
- To mount the sensor with a nut, the mouting hole diameter should be ø3.4mm.
- The hole in which the boss is inserted should be ø2.5mm (depth: 3mm or more).

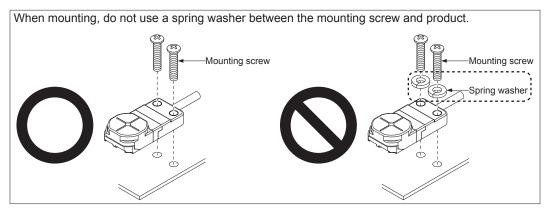




3-4 Mounting GX-F15□ and GX-H15□, GX-FL15□, GX-HL15□

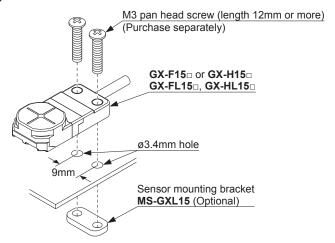
- The tightening torque should be 1N·m or less.
- To mount the sensor with a nut, the mouting hole diameter should be ø3.4mm.

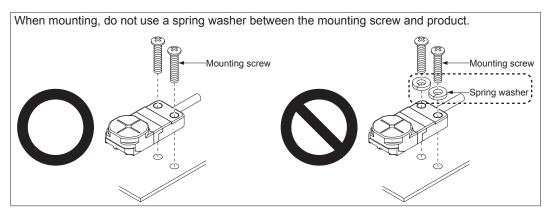




<In case of using spacer MS-GXL15 (optional)>

- The tightening torque should be 1N·m or less.
- The mouting hole diameter should be ø3.4mm.



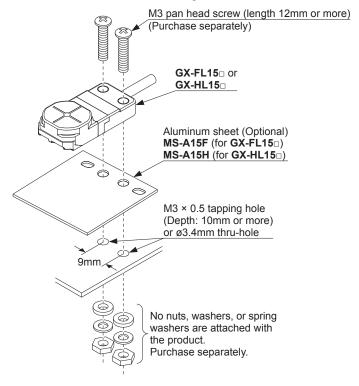


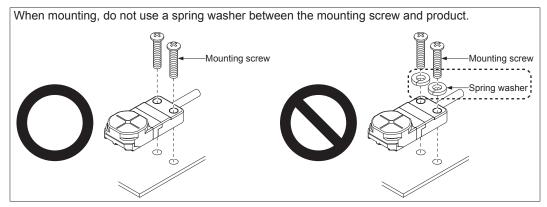
<In case of the long sensing range type GX-FL15□ or GX-HL15□>

To mount the long sensing range GX-FL15□ or GX-HL15□ on a iron or stainless steel, the enclosed aluminum sheet MS-A15F (for GX-FL15□), MS-A15H (for GX-HL15□) (optional), or any other aluminum sheet having a minimum size of 30 × 39.5 × t0.3mm (GX-FL15□), 30 × 30 × t0.3mm (GX-HL15□), should be inserted between the sensor and the magnetic body.

However, it is not necessary to use the aluminum sheet when mounting on an insulator.

- The tightening torque should be 1N·m or less.
- To mount the sensor with a nut, the mouting hole diameter should be ø3.4mm.

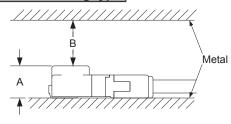


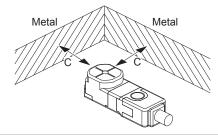


3-5 Influence of surrounding metal

 When there is a metal near the sensor, keep the minimum separation distance specified below.

Front sensing type

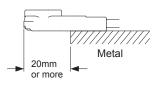




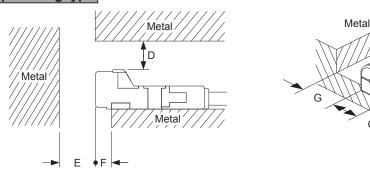
	GX-F6□	GX-F6□ GX-F8□		GX-F15□	GX-FL15 □ (Note 2)	
Α	6mm (Note 1)	7.4mm	7.1mm	8mm	8.3mm (Note 3)	
В	8mm	8mm	20mm	20mm	30mm	
С	3mm	3mm	7mm	7mm	10mm	

Notes: 1) The dimension is 6.4mm if the sensor mounting bracket **MS-GX6-1** (optional) is used.

- 2): The GX-FL15□ should be mounted on an insulator. Use the aluminum sheet MS-A15F (optional) when mounting the product to a iron or stainless steel. Furthermore, make sure that the product protrudes at least 20mm from the mounting base.
- 3): The dimension includes the thickness (0.3mm) of the aluminum sheet MS-A15F (optional).



Top sensing type

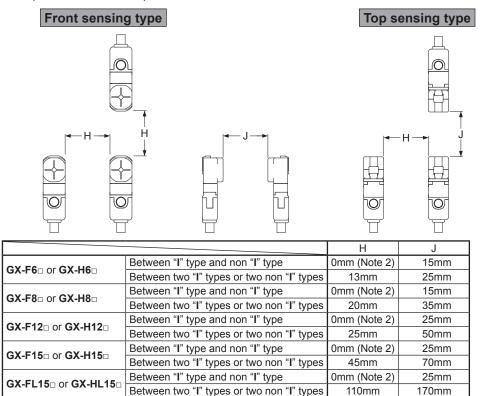


	GX-H6□	GX-H8□	GX-H12□	GX-H15□	GX-HL15□
D	3mm 4mm 7mm		7mm	6mm	12mm
Е	10mm	10mm	20mm	20mm	30mm
F	2mm 3mm		3mm	0mm	10mm (Note)
G	2mm	3mm	3mm	3mm	10mm

Note: When **GX-HL15**□ is mounted on an insulator, or seated on the enclosed aluminum sheet **MS-A15H** (optional), the distance "F" can be zero.

3-6 Mutual interference prevention

 When two or more sensors are installed in parallel or face to face, keep the minimum separation distance specified below to avoid mutual interference.



Notes: 1) "I" in the model No. specifies the different frequency type.

2): Close mounting is possible for up to two sensors. When mounting three sensors or more at an equal spacing, align the model with "I" and the model without "I" alternately. The minimum value of dimension "H" should be as given below.

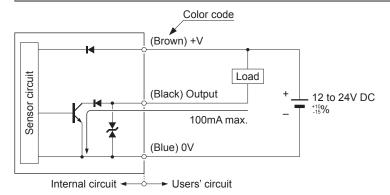
	Н
GX-F6 or GX-H6	3.5mm
GX-F8□ or GX-H8□	6mm
GX-F12 or GX-H12	6.5mm
GX-F15 or GX-H15	15mm
GX-FL15 or GX-HL15	47.5mm

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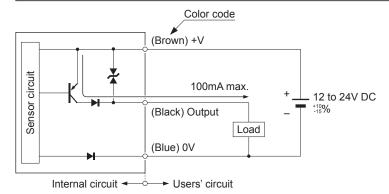
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4. I/O Circuit Diagram

NPN output type / GX-F6 / GX-H6, GX-F8 / GX-H8, GX-F12 / GX-H12 GX-F15 / GX-H15, GX-FL15 / GX-HL15



PNP output type / GX-F6=-P / GX-H6=-P, GX-F8=-P / GX-H8=-P
GX-F12=-P / GX-H12=-P, GX-F15=-P / GX-H15=-P
GX-FL15=-P / GX-HL15=-P



5. Specifications

5-1 GX-F6□, GX-H6□

T			NPN out	tput type			PNP ou	tput type	
Туре		Front s	ensing	Top se	ensing	Front s	sensing	Top se	ensing
Model No.		GX-F6A	GX-F6B	GX-H6A	GX-H6B	GX-F6A-P	GX-F6B-P	GX-H6A-P	GX-H6B-P
Different fr	equency type	GX-F6AI	GX-F6BI	GX-H6AI	GX-H6BI	GX-F6AI-P	GX-F6BI-P	GX-H6AI-P	GX-H6BI-P
Max. operat (Note 1)	tion distance	stance 1.6mm ±8%							
Stable sen (Note 1)	sing range				0 to 1	.3mm			
Standard se	ensing object				Iron sheet 12	× 12 × t1mm	ı		
Hysteresis	3		20%	or less of ope	ration distand	e (with standa	ard sensing o	bject)	
Repeatabili	ity		Along	sensing axis,	perpendicula	r to sensing a	axis: 0.04mm	or less	
Supply vol	ltage			12 to 24	V DC 10 % Ri	ipple P-P 10%	or less		
Current co	nsumption	15mA or less							
Output		 Maximum Applied volt 	ollector transi sink current: tage: 30V DC or roltage: 2V or I	100mA less (between					
Output o	peration	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed
Max. respon	se frequency				400	OHz			
Protection				IP68 (IE	C), IP68g (JE	EM) (Note 2) ((Note 3)		
Ambient te	emperature			-25 t	o +70°C, Stor	rage: -40 to +	85°C		
Ambient h	umidity			35 to	85% RH, Stor	rage: 35 to 95	% RH		
Sensing	Temperature characteristics	Over ambient temperature range –25 to +70°C: Within ±8% of sensing range at +23°C						3°C	
range variation	Voltage characteristics	Within ±2% for :18% fluctuation of the supply voltage							
Material		Enclosure: PBT, Indicator part: Polyester							
Cable		0.15mm ² 3-core oil, heat and cold resistant cabtyre cable, 1m long							
Weight					Appro	x. 15g			

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fl uctuation.

The sensing range is specified for the standard sensing object. With a non-ferrous metal, the sensing range is obtained by multiplying with the correction coeffi cient specifi ed below. Further, the sensing range also changes if the sensing object is smaller than the standard sensing object or if the sensing object is plated.

Model No.	del No. Iron Stainless steel (SUS304)		Brass	Aluminum
GX-F6□, GX-H6□	1	Approx. 0.76	Approx. 0.50	Approx. 0.48

- 2) Panasonic Industrial Devices SUNX's IP68 test method
 - 1. Immerse at 0m below 0°C water surface and leave for 30min. Then, immerse at 0m below +70°C water surface and leave for 30min.
 - 2. Regard the heat shock test in 1 as one cycle and perform 20 cycles.
 - 3. Leave in water at a depth of 1m in water for 500 hours.
 - 4. After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
- 3) If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

5-2 GX-F8□, GX-H8□

Tuna			NPN ou	tput type			PNP ou	tput type	
Туре		Front s	ensing	Top se	ensing	Front s	Front sensing		ensing
Model No.		GX-F8A	GX-F8B	GX-H8A	GX-H8B	GX-F8A-P	GX-F8B-P	GX-H8A-P	GX-H8B-P
Different fr	equency type	GX-F8AI	GX-F8BI	GX-H8AI	GX-H8BI	GX-F8AI-P	GX-F8BI-P	GX-H8AI-P	GX-H8BI-P
Max. operat (Note 1)	tion distance	2.5mm ±8%							
Stable sen (Note 1)	sing range				0 to 2	.1mm			
Standard se	ensing object				Iron sheet 15	× 15 × t1mm			
Hysteresis	;		20%	or less of ope	ration distand	e (with stand	ard sensing o	bject)	
Repeatabil	ity		Along	sensing axis,	perpendicula	r to sensing a	axis: 0.04mm	or less	
Supply vol	tage	12 to 24V DC ¹⁰ / ₁₅ % Ripple P-P 10% or less							
Current co	nsumption	15mA or less							
Output		 Maximum Applied volt 				Maximum Applied vol			
Output o	peration	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed
Max. respon	se frequency				500	Hz			•
Protection				IP68 (IE	C), IP68g (JE	EM) (Note 2)	(Note 3)		
Ambient te	emperature			-25 t	o +70°C, Sto	rage: -40 to +	85°C		
Ambient h	umidity			35 to 8	85% RH, Sto	rage: 35 to 95	% RH		
Sensing range	Temperature characteristics	Over ambient temperature range –25 to +70°C: Within ±8% of sensing range at +23°C						3°C	
variation	Voltage characteristics	. Within ±2% for *10% fluctuation of the supply voltage							
Material		Enclosure: PBT, Indicator part: Polyester							
Cable			0.15m	m ² 3-core oil,	heat and cold	d resistant cal	btyre cable, 1	m long	
Weight		Appro	x. 15g	Appro	x. 20g	Appro	x. 15g	Appro	x. 20g

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fl uctuation. The sensing range is specified for the standard sensing object. With a non-ferrous metal, the sensing range is obtained by multiplying with the correction coefficient specified below. Further, the sensing range also changes if the sensing object is smaller than the standard sensing object or if the sensing object is plated.

Model No.	Iron	Stainless steel (SUS304)	Brass	Aluminum
GX-F8□, GX-H8□	1	Approx. 0.76	Approx. 0.50	Approx. 0.48

- 2) Panasonic Industrial Devices SUNX's IP68 test method
 - Immerse at 0m below 0°C water surface and leave for 30min. Then, immerse at 0m below +70°C water surface and leave for 30min.
 - 2. Regard the heat shock test in 1 as one cycle and perform 20 cycles.
 - 3. Leave in water at a depth of 1m in water for 500 hours.
 - 4. After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
- 3) If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

5-3 GX-F12□, GX-H12□

Tuna			NPN ou	tput type			PNP ou	tput type	
Туре		Front s	ensing	Top se	ensing	Front s	sensing	Top sensing	
Model No.		GX-F12A	GX-F12B	GX-H12A	GX-H12B	GX-F12A-P	GX-F12B-P	GX-H12A-P	GX-H12B-P
Different fr	equency type	GX-F12AI	GX-F12BI	GX-H12AI	GX-H12BI	GX-F12AI-P	GX-F12BI-P	GX-H12AI-P	GX-H12BI-P
Max. operat (Note 1)	ion distance 4.0mm ±8%								
Stable sen (Note 1)	sing range				0 to 3	.3mm			
Standard se	ensing object				Iron sheet 20	× 20 × t1mm			
Hysteresis	;		20%	or less of ope	ration distand	e (with stand	ard sensing o	bject)	
Repeatabili	ity		Along	sensing axis,	perpendicula	r to sensing a	axis: 0.04mm	or less	
Supply vol	tage			12 to 24	V DC +10 % R	ipple P-P 10%	or less		
Current co	nsumption	15mA or less							
Output		 Maximum Applied vol 							
Output o	peration	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed
Max. respon	se frequency				500)Hz			,
Protection				IP68 (IE	C), IP68g (JI	EM) (Note 2)	(Note 3)		
Ambient te	emperature			-25 t	o +70°C, Sto	rage: -40 to +	85°C		
Ambient h	umidity			35 to	85% RH, Sto	rage: 35 to 95	% RH		
Sensing range	Temperature characteristics	Over ambient temperature range –25 to +70°C: Within ±8% of sensing range at +23°C						3°C	
variation	Voltage characteristics	Within ±2% for *10% fluctuation of the supply voltage							
Material	Material Enclosure: PBT, Indicator p				icator part: Po	olyester			
Cable		0.15mm ² 3-core oil, heat and cold resistant cabtyre cable, 1m long							
Weight					Appro	x. 20g			

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fl uctuation. The sensing range is specified for the standard sensing object. With a non-ferrous metal, the sensing range is obtained by multiplying with the correction coefficient specified below. Further, the sensing range also changes if the sensing object is smaller than the standard sensing object or if the sensing object is plated.

Model No.	Iron	Stainless steel (SUS304)	Brass	Aluminum
GX-F12□, GX-H12□	1	Approx. 0.79	Approx. 0.56	Approx. 0.53

- 2) Panasonic Industrial Devices SUNX's IP68 test method
 - 1. Immerse at 0m below 0°C water surface and leave for 30min. Then, immerse at 0m below +70°C water surface and leave for 30min.
 - 2. Regard the heat shock test in 1 as one cycle and perform 20 cycles.
 - 3. Leave in water at a depth of 1m in water for 500 hours.
 - 4. After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
- If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

5-4 GX-F15□, GX-H15□

Tuna			NPN ou	tput type			PNP ou	tput type	
Туре		Front s	ensing	Top se	ensing	Front sensing		Top se	ensing
Model No.		GX-F15A	GX-F15B	GX-H15A	GX-H15B	GX-F15A-P	GX-F15B-P	GX-H15A-P	GX-H15B-P
Different fr	equency type	GX-F15AI	GX-F15BI	GX-H15AI	GX-H15BI	GX-F15AI-P	GX-F15BI-P	GX-H15AI-P	GX-H15BI-P
Max. operat (Note 1)	tion distance	5.0mm ±8%							
Stable sen (Note 1)	sing range				0 to 4	.2mm			
Standard se	ensing object				Iron sheet 20	× 20 × t1mm			
Hysteresis	;		20%	or less of ope	ration distand	e (with stand	ard sensing o	bject)	
Repeatabil	ity		Along	sensing axis,	perpendicula	r to sensing a	axis: 0.04mm	or less	
Supply vol	tage	12 to 24V DC ∹i⁰ Ripple P-P 10% or less							
Current co	nsumption	15mA or less							
Output		 Maximum Applied vol 				Maximum Applied vol			
Output o	peration	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed
Max. respon	se frequency				250)Hz			
Protection				IP68 (IE	C), IP68g (JE	EM) (Note 2)	(Note 3)		
Ambient te	emperature			-25 t	o +70°C, Sto	rage: -40 to +	85°C		
Ambient h	umidity			35 to	85% RH, Sto	rage: 35 to 95	5% RH		
Sensing range	Temperature characteristics	Over ambient temperature range –25 to +70°C: Within ±8% of sensing range at +23°C						3°C	
variation	Voltage characteristics	Within ±2% for :18% fluctuation of the supply voltage							
Material		Enclosure: PBT, Indicator part: Polyester							
Cable		0.15mm ² 3-core oil, heat and cold resistant cabtyre cable, 1m long							
Weight					Appro	x. 20g			

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fl uctuation. The sensing range is specified for the standard sensing object. With a non-ferrous metal, the sensing range is obtained by multiplying with the correction coefficient specified below. Further, the sensing range also changes if the sensing object is smaller than the standard sensing object or if the sensing object is plated.

Model No.	Iron	Stainless steel (SUS304)	Brass	Aluminum
GX-F15 _□ , GX-H15 _□	1	Approx. 0.68	Approx. 0.47	Approx. 0.45

- 2) Panasonic Industrial Devices SUNX's IP68 test method
 - 1. Immerse at 0m below 0°C water surface and leave for 30min. Then, immerse at 0m below +70°C water surface and leave for 30min.
 - 2. Regard the heat shock test in 1 as one cycle and perform 20 cycles.
 - 3. Leave in water at a depth of 1m in water for 500 hours.
 - 4. After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
- 3) If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

5-5 GX-FL15□, GX-HL15□

Туре		Long sensing range type								
		NPN output type				PNP output type				
		Front sensing		Top sensing		Front sensing		Top sensing		
Model No.		GX-FL15A	GX-FL15B	GX-HL15A	GX-HL15B	GX-FL15A-P	GX-FL15B-P	GX-HL15A-P	GX-HL15B-P	
Different fr	equency type	GX-FL15AI	GX-FL15BI	GX-HL15AI	GX-HL15BI	GX-FL15AI-P	GX-FL15BI-P	GX-HL15AI-P	GX-HL15BI-P	
Max. operation distance (Note 1)		8.0mm ±8% (Note 2)								
Stable sensing range (Note 1)		0 to 6.7mm (Note 2)								
Standard sensing object		Iron sheet 30 × 30 × t1mm								
Hysteresis		20% or less of operation distance (with standard sensing object)								
Repeatability		Along sensing axis, perpendicular to sensing axis: 0.04mm or less								
Supply voltage		12 to 24V DC ¹⁰ / ₁₅ % Ripple P-P 10% or less								
Current consumption		15mA or less								
Output		NPN open-collector transistor • Maximum sink current: 100mA • Applied voltage: 30V DC or less (between output and 0V) • Residual voltage: 2V or less (at 100mA sink current)				PNP open-collector transistor • Maximum source current: 100mA • Applied voltage: 30V DC or less (between output and +V) • Residual voltage: 2V or less (at 100mA source current)				
Output operation		Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed	Normally open	Normally closed	
Max. respon	se frequency	150Hz (Note 3)								
Protection		IP68 (IEC), IP68g (JEM) (Note 4) (Note 5)								
Ambient te	emperature	-25 to +70°C, Storage: -40 to +85°C								
Ambient humidity		35 to 85% RH, Storage: 35 to 95% RH								
Sensing range variation	Temperature characteristics	Over ambient temperature range –25 to +70°C: Within ±8% of sensing range at +23°C								
	Voltage characteristics	Within ±2% for :10% fluctuation of the supply voltage								
Material		Enclosure: PBT, Indicator part: Polyester								
Cable		0.15mm ² 3-core oil, heat and cold resistant cabtyre cable, 1m long								
Weight		Approx. 20g								

Notes: 1) The maximum operation distance stands for the maximum distance for which the sensor can detect the standard sensing object.

The stable sensing range stands for the sensing range for which the sensor can stably detect the standard sensing object even if there is an ambient temperature drift and/or supply voltage fl uctuation.

The sensing range is specifi ed for the standard sensing object. With a non-ferrous metal, the sensing range is obtained by multiplying with the correction coeffi cient specifi ed below. Further, the sensing range also changes if the sensing object is smaller than the standard sensing object or if the sensing object is plated.

<Correction coeffi cient>

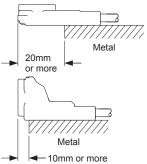
Model No.	Iron	Stainless steel (SUS304)	Brass	Aluminum	
GX-FL15□	1	Approx. 0.70	Approx. 0.45	Approx. 0.43	
GX-HL15□	1	Approx. 0.76	Approx. 0.50	Approx. 0.48	

It is recommended that the **GX-FL15** \square and the **GX-HL15** \square be installed on an insulator. Note that when a sensor is installed on copper or aluminum, for example, the sensing range is obtained by multiplying with the correction coefficient specified below.

When installing the GX-FL15
 on steel or stainless steel
 Ensure that the front end protrudes at least 20mm, as shown in
 the figure at right.
 Refer to the table below for the correction coefficient.

When installing the GX-HL15□ on steel or stainless steel
 Ensure that the front end protrudes at least 10mm, as shown in
 the figure at right.

Refer to the table below for the correction coefficient.



If the sensor cannot be installed with the front end protruding
 Use aluminum sheet MS-A15F (for GX-FL15
) or MS-A15H (for GX-HL15
) (to be purchased separately) inserted between the sensor and the mounting plate.
 Refer to the table below for the correction coefficient.

<Correction coeffi cient>

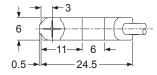
Mounting condition	Model No.	Insulator	Iron	Stainless steel (SUS304)	Brass	Aluminum
Normal installation	GX-FL15□	1.0	-	_	Approx. 0.94	Approx. 0.93
INOITHAI IIIStallation	GX-HL15□	1.0	_	_	Approx. 1.05	Approx. 1.04
The end must protrude at least 20mm from the mounting base.	GX-FL15□	-	Approx. 1.02	Approx. 0.99	-	-
The end must protrude at least 10mm from the mounting base.	GX-HL15□	-	Approx. 1.04	Approx. 1.00	-	-
Use the aluminum	GX-FL15□	-	Approx. 0.92	Approx. 0.92	-	_
sheet (optional).	GX-HL15□	_	Approx. 1.08	Approx. 1.05	_	_

- 2) Each value shows the required space of the product mounted to insulators directly. In the case of mounting the product to a steel or stainless mounting plate, insert the optional aluminum sheet MS-A15F (for the GX-FL15□) or MS-A15H (for GX-HL15□) between the sensor and the mounting plate.
- Each value shows the required space of the product mounted to insulators directly. The maximum response frequency will be 100Hz if the product is mounted to a steel or stainless mounting plate.
- 4) Panasonic Industrial Devices SUNX's IP68 test method
 - Immerse at 0m below 0°C water surface and leave for 30min. Then, immerse at 0m below +70°C water surface and leave for 30min.
 - 2. Regard the heat shock test in 1 as one cycle and perform 20 cycles.
 - 3. Leave in water at a depth of 1m in water for 500 hours.
 - 4. After tests 1 to 3, insulation resistance, voltage withstandability, current consumption, and sensing ranges must meet the standard values.
- If using the sensor in an environment where cutting oil droplets splatter, the sensor may deteriorate due to added substances in the oil.

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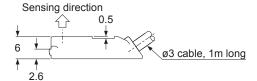
6. Dimensions

GX-F6□

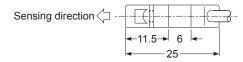


(Unit: mm)



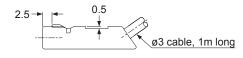


GX-H6□

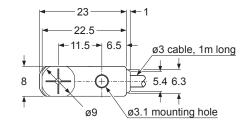


(Unit: mm)



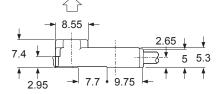


GX-F8□



(Unit: mm)

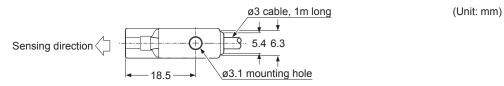


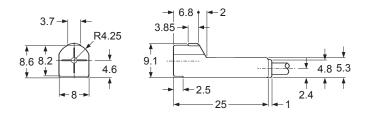


Sensing direction

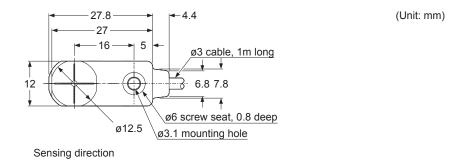


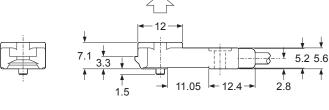
GX-H8□

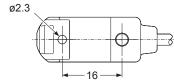




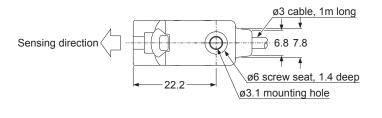
GX-F12

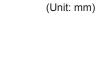


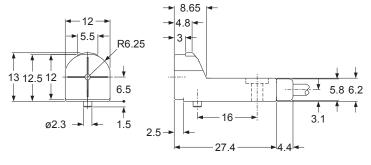




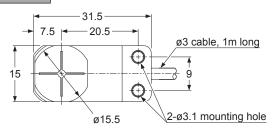
GX-H12□





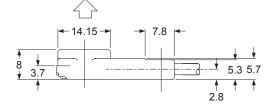


GX-F15□, GX-FL15□



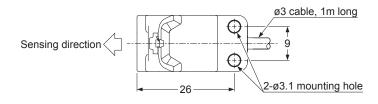




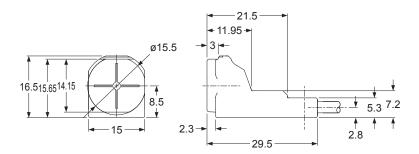


Sensing direction

GX-H15□, GX-HL15□



(Unit: mm)



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