

# DCS880

## DCS880 Quick guide



# List of manuals

	Publication number	Language						
		E	D	I	ES	F	CN	RU
<b>DCS880 Quick Guide</b>	3ADW000480	x						
<b>DCS880 Units</b>								
DCS880 Flyer	<a href="#">3ADW000475</a>	x	x					
DCS880 Technical Catalog	3ADW000465	x						
DCS880 Hardware Manual	3ADW000462	x						
DCS880 Firmware Manual	<a href="#">3ADW000474</a>	x						
DCS880 Service Manual	3ADW000488	p						
ACS-AP-x assistant control panels user's manual	<a href="#">3AUA0000085685</a>	x						
Adaptive programming, Application guide	<a href="#">3AXD5000028574</a>	x						
<b>Option manuals and guides</b>								
SDCS-DPI-H01 panel bus adapter module	HW DCT880 0001E	x						
<b>Door mounting kits</b>								
DPMP-01 mounting platform for ACS-AP control panel	<a href="#">3AUA0000100140</a>	x						
DPMP-02 mounting platform for ACS-AP control panel	<a href="#">3AUA0000136205</a>	x						
<b>Serial communication</b>								
FCAN-01 CANopen adapter module	<a href="#">3AFE68615500</a> <a href="#">3AUA0000121752</a>	x		x				
FDNA-01 DeviceNet™ adapter module	<a href="#">3AFE68573360</a>	x						
FECA-01 EtherCAT adapter module	<a href="#">3AUA0000068940</a> <a href="#">3AUA0000083936</a>	x		x				
FENA-01/-11/-21 Ethernet adapter module	<a href="#">3AUA0000093568</a>	x						
FEPL-02 Ethernet POWERLINK adapter module	<a href="#">3AUA0000123527</a> <a href="#">3AUA0000133138</a>	x		x				
FPBA-01 PROFIBUS DP adapter module	<a href="#">3AFE68573271</a> <a href="#">3AFE68989078</a>	x		x				
FSCA-01 RS-485 adapter module	<a href="#">3AUA0000109533</a>	x						
FDCO-01/02 DDCS communication modules	<a href="#">3AUA0000114058</a>							
Drive (IEC61131-3) application programming manual	<a href="#">3AUA0000127808</a>	x						
<b>Tool and maintenance manuals and guides</b>								
Drive composer PC tool	<a href="#">3AUA0000094606</a>	x						
NETA-21 remote monitoring tool	<a href="#">3AUA0000096939</a>	x						
NETA-21 remote monitoring tool installation and startup guide	<a href="#">3AUA0000096881</a>	x						
<b>Extension modules</b>								
FIO-11 Analog extension module	<a href="#">3AFE68784930</a>							
FIO-01 Digital extension modules	<a href="#">3AFE68784921</a>							
FAIO-01 Analag extension module	<a href="#">3AUA0000124968</a>							
FEN-01 TTL encoder interface	<a href="#">3AFE68784603</a>							
FEN-31 HTL encoder interface	<a href="#">3AUA0000031044</a>							
FEA-01 F-series Extension Adapter	<a href="#">3AUA0000071412</a>							
FEA-03 F series extension adapter	<a href="#">3AUA0000115811</a>							
x → existing      p → planned								
Status 06.2017								

DCS880 Manuals list e.c.docx

## DCS880

All information are available on the Internet by following links:

- DCS880 documentation



[www.abb.com](http://www.abb.com) → Search for DCS880  
Direct link: [DCS880 CD download](#)

- ABB Drive composer entry PC tool for parameterization, commissioning and service



[www.abb.com](http://www.abb.com) → Search for drive composer  
Direct link: [ABB Drive composer](#)

# Table of contents

<b>List of manuals</b>	<b>2</b>
DCS880 .....	2
<b>Table of contents</b>	<b>3</b>
<b>Safety instructions</b>	<b>4</b>
What this chapter contains .....	4
To which products this chapter applies .....	4
Use of warnings and notes .....	4
Installation and maintenance work .....	4
Grounding .....	5
Printed circuit boards and fiber optic cables .....	5
Mechanical installation.....	6
Operation .....	6
<b>Type code</b>	<b>7</b>
<b>Plus codes</b>	<b>8</b>
<b>Environmental conditions</b>	<b>9</b>
<b>Ratings</b>	<b>10</b>
<b>Planning the electrical installation</b>	<b>11</b>
Converters size H1 ... H4 configuration using an OnBoard field exciter .....	11
Cross-sectional areas - Tightening torques.....	12
<b>Mechanical installation</b>	<b>13</b>
Dimensioning and weights.....	14
<b>Technical data</b>	<b>15</b>
Control circuit terminals on the SDCS-CON-H01 .....	15
Location of the control circuit board SDCS-CON-H01 .....	15
Control circuit terminal layout .....	16
<b>Using the control panel</b>	<b>17</b>
Basic operation .....	17
Control panel navigation .....	17
Home view .....	18
Common user tasks.....	19
DCS880 Set up control panel assistant.....	20
<b>Set UP Procedure</b>	<b>21</b>
Checking prior to powering On .....	21
Power ON and check.....	21
<b>PC-tool "Drive composer entry"</b>	<b>22</b>
<b>Drive composer pro DCS880 assistant</b>	<b>24</b>
<b>Parameters</b>	<b>25</b>
What this chapter contains .....	25
Terms and abbreviations .....	25
Summary of parameter groups.....	25
<b>Drive logic</b>	<b>27</b>
<b>Fieldbus control</b>	<b>28</b>
<b>Firmware structure diagrams</b>	<b>29</b>

# Safety instructions

## What this chapter contains

This chapter contains the safety instructions which you must follow when installing, operating and servicing the drive. If ignored, physical injury or death may follow, or damage may occur to the drive, the motor or driven equipment. Read the safety instructions before you work on the unit.

## To which products this chapter applies

The information is valid for the whole range of the product DCS880, the converter modules DCS880-S0x size H1 ... H8, field exciter units DCF80x, etc. like the Rebuild Kit DCS800-R00.

## Use of warnings and notes

There are two types of safety instructions throughout this manual: warnings and notes. Warnings caution you about conditions which can result in serious injury or death and/or damage to the equipment and advice on how to avoid the danger. Notes draw attention to a particular condition or fact, or give information on a subject. The warning symbols are used as follows:



**Dangerous voltage warning** warns of high voltage which can cause physical injury and/or damage to the equipment.



**General danger warning** warns about conditions, other than those caused by electricity, which can result in physical injury or death and/or damage to the equipment.



**Electrostatic sensitive discharge warning** warns of electrostatic discharge which can damage the equipment.

## Installation and maintenance work

These warnings are intended for all who work on the drive, motor cable or motor. Ignoring the instructions can cause physical injury or death and/or damage to the equipment.



### WARNING

- Only qualified electricians are allowed to install and maintain the drive!
- Never work on the drive, motor cable or motor when main power is applied. Always ensure by measuring with a multimeter (impedance at least 1 Mohm) that:
  1. Voltage between drive input phases U1, V1 and W1 and the frame is close to 0 V.
  2. Voltage between terminals C+ and D- and the frame is close to 0 V.
- Do not work on the control cables when power is applied to the drive or to the external control circuits. Externally supplied control circuits may cause dangerous voltages inside the drive even when the main power on the drive is switched off.
- Do not make any insulation resistance or voltage withstand tests on the drive or drive modules.
- Isolate the motor cables from the drive when testing the insulation resistance or voltage withstand of the cables or the motor.
- When reconnecting the motor cable, always check that the C+ and D- cables are connected with the proper terminal.

### Note:

- The motor cable terminals on the drive are at a dangerously high voltage when the main power is on, regardless of whether the motor is running or not.
- Depending on the external wiring, dangerous voltages (115 V, 220 V or 230 V) may be present on the relay outputs of the drive system (e.g. XRO1 ... XRO3).
- DCS880 with enclosure extension: Before working on the drive, isolate the whole drive from the supply.

## Grounding



These instructions are intended for all who are responsible for the grounding of the drive. Incorrect grounding can cause physical injury, death and/or equipment malfunction and increase electromagnetic interference.



### WARNING

- Ground the drive, motor and adjoining equipment to ensure personnel safety in all circumstances, and to reduce electromagnetic emission and pick-up.
- Make sure that grounding conductors are adequately sized and marked as required by safety regulations.
- In a multiple-drive installation, connect each drive separately to protective earth (PE).
- Minimize EMC emission and make a 360° high frequency grounding (e.g. conductive sleeves) of screened cable entries at the cabinet lead-through plate.
- Do not install a drive equipped with an EMC filter to an ungrounded power system or a high resistance-grounded (> 30 ohms) power system.

### Note:

- Power cable shields are suitable as equipment grounding conductors only when adequately sized to meet safety regulations.
- As the normal leakage current of the drive is higher than 3.5 mAAC or 10 mADC (stated by EN 50178, 5.2.11.1), a fixed protective earth connection is required.

## Printed circuit boards and fiber optic cables

These instructions are intended for all who handle the circuit boards and fiber optic cables. Ignoring the following instructions can cause damage to the equipment.



### WARNING

The printed circuit boards contain components sensitive to electrostatic discharge. Wear a grounding wrist band when handling the boards. Do not touch the boards unnecessarily.

Use grounding strip:

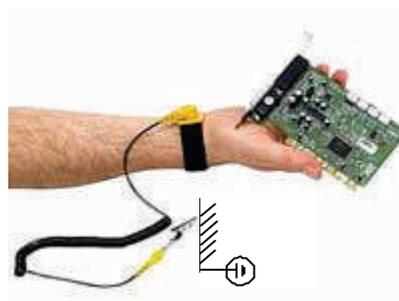


ABB order no.: 3ADV050035P0001



### WARNING

- Handle the fiber optic cables with care.
- When unplugging optic cables, always grab the connector, not the cable itself.
- Do not touch the ends of the fibers with bare hands as the fiber is extremely sensitive to dirt.
- The minimum allowed bend radius is 35 mm (1.4 in.).

## Mechanical installation

These notes are intended for all who install the drive. Handle the unit carefully to avoid damage and injury.



### WARNING

- DCS880 sizes H4 ... H8: The drive is heavy. Do not lift it alone. Do not lift the unit by the front cover. Place units H4 ... H6 only on its back.
- DCS880 sizes H6 ... H8: The drive is heavy. Lift the drive by the lifting lugs only. Do not tilt the unit. The unit will overturn from a tilt of about 6 degrees.
- Make sure that dust from drilling does not enter the drive when installing. Electrically conductive dust inside the unit may cause damage or lead to malfunction.
- Ensure sufficient cooling.
- Do not fasten the drive by riveting or welding.

## Operation

These warnings are intended for all who plan the operation of the drive or operate the drive. Ignoring the instructions can cause physical injury or death and/or damage to the equipment.



### WARNING

- Before adjusting the drive and putting it into service, make sure that the motor and all driven equipment are suitable for operation throughout the speed range provided by the drive. The drive can be adjusted to operate the motor at speeds above and below the base speed.
- Do not control the motor with the disconnecting device (disconnecting mains); instead, use the control panel keys  and , or commands via the I/O board of the drive.
- Mains connection:  
You can use a disconnect switch (with fuses) to disconnect the electrical components of the drive from the mains for installation and maintenance work. The type of disconnect switch used must be as per EN 60947-3, Class B, so as to comply with EU regulations, or a circuit-breaker type which switches off the load circuit by means of an auxiliary contact causing the breaker's main contacts to open. The mains disconnect must be locked in its "OPEN" position during any installation and maintenance work.
- EMERGENCY STOP buttons must be installed at each control desk and at all other control panels requiring an emergency stop function. Pressing the STOP button on the control panel of the drive will neither cause an emergency stop of the motor, nor will the drive be disconnected from any dangerous potential.
- To avoid unintentional operating states, or to shut the unit down in case of any imminent danger according to the standards in the safety instructions it is not sufficient to merely shut down the drive via signals "RUN", "drive OFF" or "Emergency Stop" respectively "control panel" or "PC tool".
- Intended use:  
The operating instructions cannot take into consideration every possible case of configuration, operation or maintenance. Thus, they mainly give such advice only, which is required by qualified personnel for normal operation of the machines and devices in industrial installations.
- If in special cases the electrical machines and devices are intended for use in non-industrial installations - which may require stricter safety regulations (e.g. protection against contact by children or similar) - these additional safety measures for the installation must be provided by the customer during assembly.

### Note:

- When the control location is not set to Local (Local not shown in the status row of the display), the stop key on the control panel will not stop the drive. To stop the drive using the control panel, press the Loc/Rem key and then the stop key .

## Type code

The type code contains information on the specification and configuration of the drive. The first digits from left show the basic configuration (e.g. DCS880-S01-2000). The optional selections are given thereafter on the name plate by plus code. The main selections are described below. Not all selections are available for all types.

The drive's basic type code: DCS880-AAB-CCCC-DDEF + plus code			
<b>Product family</b>	DCS8 80		
<b>Product type:</b>	AA	= S0 = R0 = E0 = A0	Standard converter module Rebuild kit Panel solution Enclosed converter
<b>Bridge type:</b>	B	= 1 = 2	Single bridge (2-Q) 2 anti-parallel bridges (4-Q)
<b>Module type:</b>	CCCC	=	Rated DC current (IP00)
<b>Rated AC voltage:</b>	DD	= 04 = 05 = 06 = 07 = 08 = 10 = 12	100 V <sub>AC</sub> - 415 V <sub>AC</sub> 100 V <sub>AC</sub> - 525 V <sub>AC</sub> 270 V <sub>AC</sub> - 600 V <sub>AC</sub> 315 V <sub>AC</sub> - 690 V <sub>AC</sub> 360 V <sub>AC</sub> - 800 V <sub>AC</sub> 450 V <sub>AC</sub> - 990 V <sub>AC</sub> 540 V <sub>AC</sub> - 1200 V <sub>AC</sub>
<b>Power connection:</b>	E	= X = L = R	Standard H1 ... H7 Left side H8 Right side H8
<b>Revision code:</b>	F	= 0	1 <sup>st</sup> generation
<b>Field exciter configuration:</b>		+0S163 +S164	H1 ... H4 without OnBoard field exciter H5 and H6 with internal field exciter, supply external (H5 and H6: 25 A, Rebuild kit: 16 A / 25 A)
<b>Fan voltage:</b>		Standard +S171	<b>Size H4</b> Fan voltage: 230 V / 1-ph Fan voltage: 115 V / 1-ph
<b>Application programming</b>		+S551	Memory unit including drive application programming license
<b>Current measurement:</b>		+S175	SDCS-CMA-2 (H6 ... H8)
<b>Voltage measurement:</b>		+S186 +S185 +S183 +S189	120 V SDCS-SUB-4 (H1 ... H5) SDCS-PIN-H51 configured to 120 V (H6 ... H8) SDCS-PIN-H51 configured to 990 V (H6 ... H8), 12-pulse serial / serial sequential SDCS-PIN-H51 configured to galvanic isolation (H6 ... H8)
<b>SDCS-DSL-H1x:</b>		+S521 +S522 +S523	1 DCsLink channel, 0 channels optical power link SDCS-DSL-H10 1 DCsLink channel, 2 channels optical power link SDCS-DSL-H12 1 DCsLink channel, 4 channels optical power link SDCS-DSL-H14
<b>Control panel:</b>		+0J404 +J428 +J429	Without control panel daisy-chain option DPI-H01 kit Bluetooth control panel ACS-AP-W

The technical data and specifications are valid as of going to press. ABB reserves the right to make subsequent alterations.

## Plus codes

Option	Option code	Description
ACS-AP-I	standard	Control panel built-in
no ACS-AP-I	0J404	No control panel
ACS-AP-W	+J429	Bluetooth control panel
DPI-H01	+J428	daisy-chain option
FDNA-01	+K451	Fieldbus DeviceNet
FPBA-01	+K454	Fieldbus PROFIBUS
FCAN-01	+K457	Fieldbus CANOpen
FSCA-01	+K458	Fieldbus Modbus
FCNA-01	+K462	Fieldbus ControlNet
FECA-01	+K469	Fieldbus EtherCat
FEPL-02	+K470	Fieldbus Ethernet POWERLINK
FENA-11	+K473	Ethernet/IP, Modbus/TCP, Profinet
FENA-21	+K475	Ethernet/IP, Modbus/TCP, Profinet
FIO-11	+L500	Analog I/O Extension (3 AI, 1 AO, 2 DIO)
FIO-01	+L501	Digital I/O Extension (4 DIO, 2 RO)
FAIO-01	+L525	Analog I/O Extension (2 AI, 2 AO)
FDIO-01	+L526	Digital I/O Extension (3 DI, 2 RO)
FPTC-01	+L536	Thermistor protection module
FEN-31	+L502	HTL Encoder Interface
FEN-21	+L516	Resolver Interface
FEN-01	+L517	TTL Encoder interface
FEN-11	+L518	Absolute Encoder Interface
FDCO-01	+L503	DDCS communication 10/10 MBd
Application programming	+S551	Memory unit including drive application programming license

## Environmental conditions

System connections	
Voltage, 3-phase:	100 ... ≤ 1000 V acc. to IEC 60038
Voltage deviation:	±10 % continuous; ±15% short-time *
Rated frequency:	50 Hz or 60 Hz
Static frequency deviation:	50 Hz ± 2 %; 60 Hz ± 2 %
Dynamic: frequency range:	50 Hz ± 5 Hz; 60 Hz ± 5 Hz
df/dt:	17 % / s
* = 0.5 ... 30 cycles	
<b>Please note:</b> Special consideration must be taken for voltage deviation in regenerative mode.	
Degree of protection	
Converter module and options (line chokes, fuse holder, field exciter, etc.):	IP 00
Enclosed converters:	IP 20/21/31/41
Paint finish	
Converter module:	Body RAL 7012; Cover RAL 9017 & RAL 9002
Enclosed converter:	Light grey RAL 7035

### Sound pressure level and vibration

Size	Sound pressure level L <sub>p</sub> (1 m distance)		Vibration
	as module	enclosed conv.	
H1	55 dBA	68 dBA	3 mm, 2 ... 9 Hz 1 g, 9 ... 200 Hz
H2	55 dBA	72 dBA	
H3	60 dBA	78 dBA	
H4	66 ... 70 dBA, depending on fan	77 dBA	

Environmental limit values	
Permissible cooling air temp.	
- at converter module air inlet:	0 ... +55°C
with rated DC current:	0 ... +40°C
with different DC current:	+30 ... +55°C
- Options:	0 ... +40°C
Relative humidity (at 5...+40°C):	5 ... 95 %, no condensation
Relative humidity (at 0...+5°C):	5 ... 50 %, no condensation
Change of the ambient temp.:	< 0.5°C / minute
Storage temperature:	-40 ... +55°C
Transport temperature:	-40 ... +70°C
Pollution degree (IEC 60664-1, IEC 60439-1).	2
Site elevation	
< 1000 m above M.S.L.:	100 %, without current reduction
> 1000 m above M.S.L.:	with current reduction,

### North American Standards

In North America the system components fulfil the requirements of the table below

Rated supply voltage	Standards	
	Converter module	Enclosed converter
to 990 V	UL 61800-5-1 Power Conversion Equipment CSA C 22.2 No. 274-13 Industrial Control Equipment, Industrial Products Available for converter modules including field exciter units. Types with UL mark: • see UL Listing <a href="http://www.ul.com">www.ul.com</a> / certificate no. E196914 • or on request	UL/CSA types: on request

# Ratings

## Current and power ratings

See the current ratings including several standard duty cycles for the DCS880 with 50 Hz and 60 Hz supplies below. The current ratings are based on an ambient temperature of maximum 40°C and an elevation of maximum 1000 m above mean sea level:

Unit type	I <sub>DC I</sub>	I <sub>DC II</sub>		I <sub>DC III</sub>		I <sub>DC IV</sub>		Size	Internal field current
		100 % 15 min	150 % 60 s	100 % 15 min	150 % 120 s	100 % 15 min	200 % 10 s		
<b>2-Q converters</b>	continuous								
<b>400 V / 500 V / 525 V</b>	[A]	[A]		[A]		[A]			
DCS880-S01-0020-04/05**	20	16	24	16	24	15	30	H1	0.3 ... 6 A
DCS880-S01-0045-04/05**	45	36	54	35	52	31	62		1 ... 12 A
DCS880-S01-0065-04/05**	65	54	81	52	78	49	98		
DCS880-S01-0090-04/05**	90	76	114	74	111	73	146		
DCS880-S01-0135-04/05	135	105	157	100	150	93	186	H2	
DCS880-S01-0180-04/05**	180	130	195	125	187	110	220		
DCS880-S01-0225-04/05	225	170	255	165	247	148	296		
DCS880-S01-0270-04/05	270	200	300	195	292	180	360		
DCS880-S01-0315-04/05**	315	240	360	235	352	215	430	H3	2 ... 25 A
DCS880-S01-0405-04/05**	405	310	465	300	450	270	540		
DCS880-S01-0470-04/05	470	350	525	340	510	310	620		
DCS880-S01-0610-04/05**	610	455	682	435	652	425	850		
DCS880-S01-0740-04/05	740	570	855	540	810	525	1050	H4	2 ... 30 A
DCS880-S01-0900-04/05	900	680	1020	650	975	615	1230		
<b>600 V / 690 V</b>									
DCS880-S01-0290-06	290	240	360	225	337	205	410	H3	-
DCS880-S01-0590-06	590	470	705	472	708	434	868	H4	-

\*\* This unit type can be used as large field exciter. Do not forget the SDCS-DSL-H1x (+S199).  
A 10 % current de-rating is strongly recommended.

### Notes:

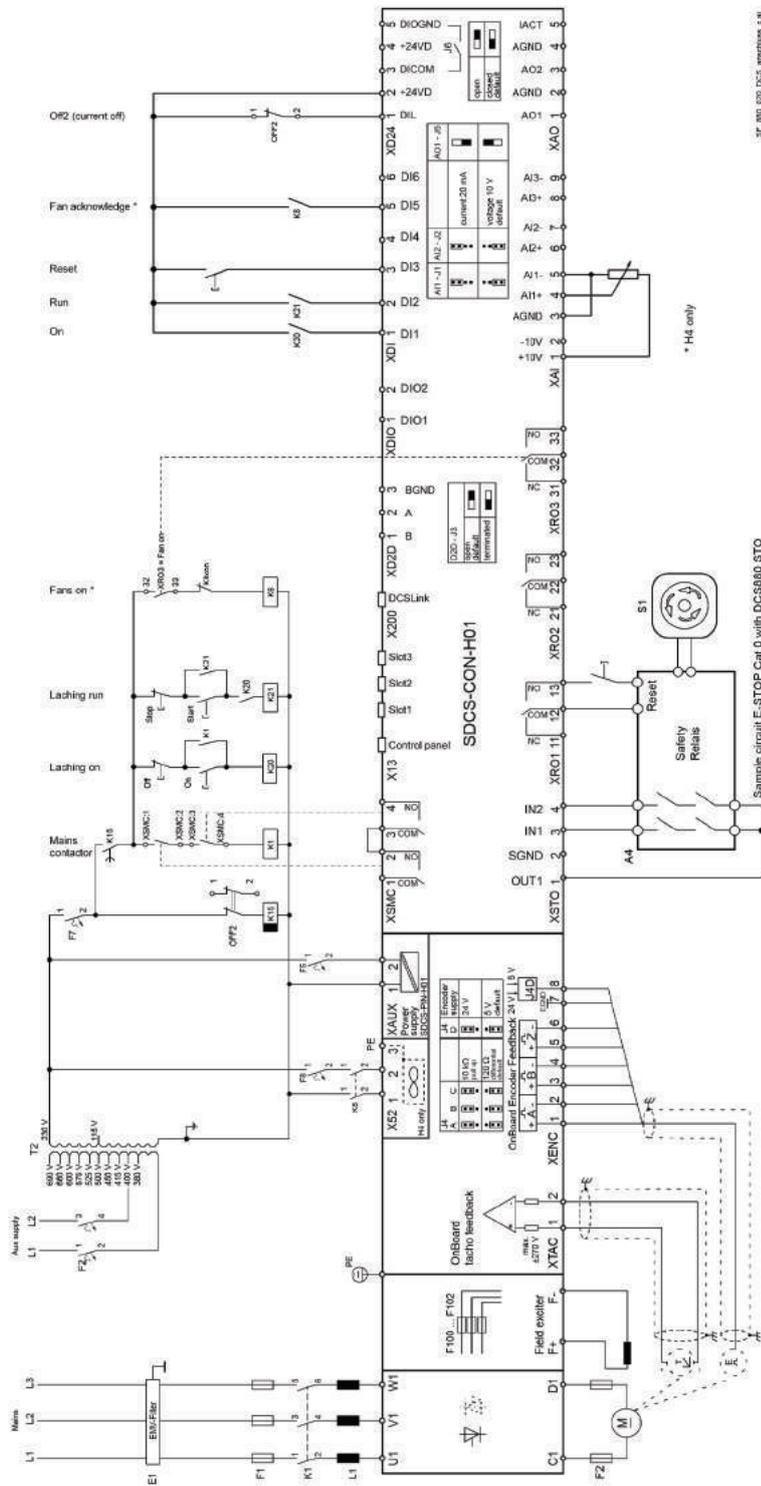
AC current IAC = 0.82 \* IDC

Unit type	I <sub>DC I</sub>	I <sub>DC II</sub>		I <sub>DC III</sub>		I <sub>DC IV</sub>		Size	Internal field current
		100 % 15 min	150 % 60 s	100 % 15 min	150 % 120 s	100 % 15 min	200 % 10 s		
<b>4-Q converters</b>	continuous								
<b>400 V / 525 V</b>	[A]	[A]		[A]		[A]			
DCS880-S02-0025-04/05**	25	22	33	21	31	20	40	H1	0.3 ... 6 A
DCS880-S02-0050-04/05**	50	38	57	37	55	33	66		1 ... 12 A
DCS880-S02-0075-04/05**	75	60	90	59	88	54	108		
DCS880-S02-0100-04/05**	100	85	127	83	124	80	160		
DCS880-S02-0150-04/05	150	114	171	110	165	100	200	H2	
DCS880-S02-0200-04/05**	200	145	217	140	210	115	230		
DCS880-S02-0250-04/05	250	185	277	180	270	165	330		
DCS880-S02-0300-04/05	300	225	337	220	330	200	400		
DCS880-S02-0350-04/05**	350	275	412	265	397	245	490	H3	2 ... 25 A
DCS880-S02-0450-04/05**	450	350	525	340	510	310	620		
DCS880-S02-0520-04/05	520	400	600	380	570	350	700		
DCS880-S02-0680-04/05**	680	525	787	510	765	475	950		
DCS880-S02-0820-04/05	820	630	945	610	915	565	1130	H4	2 ... 30 A
DCS880-S02-1000-04/05	1000	750	1125	725	1087	660	1320		
<b>600 V / 690 V</b>									
DCS880-S02-0320-06	320	256	384	246	369	235	470	H3	-
DCS880-S02-0650-06	650	514	771	508	762	462	924	H4	-

# Planning the electrical installation

## Converters size H1 ... H4 configuration using an OnBoard field exciter

Wiring the drive according to this diagram offers the highest degree of monitoring functions done by the drive.



## Cross-sectional areas - Tightening torques

Recommended cross-sectional area to DINVDE 0276-1000 and DINVDE 0100-540 (PE) trefoil arrangement, up to 50°C ambient temperature.

Armature:

Converter type	C1, D1			U1, V1, W1			PE		[Nm]
	$I_{DC}$ [A-]	1 [mm <sup>2</sup> ] 	(2.) [mm <sup>2</sup> ] 	$I_V$ [A~]	1 [mm <sup>2</sup> ] 	(2.) [mm <sup>2</sup> ] 	[mm <sup>2</sup> ] 		
DCS880-S0x-0025-xx	25	1 x 6	-	21	1 x 4	-	1x 4	1 x M6	6
DCS880-S0x-0050-xx	50	1 x 10	-	41	1 x 6	-	1x 6	1 x M6	6
DCS880-S0x-0075-xx	75	1 x 25	-	61	1 x 25	-	1x 16	1 x M6	6
DCS880-S0x-0100-xx	100	1 x 25	-	82	1 x 25	-	1x 16	1 x M6	6
DCS880-S0x-0150-xx	150	1 x 35	-	114	1 x 35	-	1x 16	1 x M10	25
DCS880-S0x-0200-xx	200	2 x 35	1 x 95	163	2 x 25	1 x 95	1x 25	1 x M10	25
DCS880-S0x-0250-xx	250	2 x 35	1 x 95	204	2 x 25	1 x 95	1x 25	1 x M10	25
DCS880-S0x-0300-xx	300	2 x 70	1 x 95	220	2 x 50	1 x 95	1x 50	1 x M10	25
DCS880-S0x-0320-xx	320	2 x 70	1 x 95	220	2 x 50	1 x 95	1x 50	1 x M10	25
DCS880-S0x-0350-xx	350	2 x 70	-	286	2 x 50	-	1x 50	1 x M10	25
DCS880-S0x-0450-xx	450	2 x 95	-	367	2 x 95	-	1x 50	1 x M10	25
DCS880-S0x-0520-xx	520	2 x 95	-	424	2 x 95	-	1x 50	1 x M10	25
DCS880-S0x-0650-xx	650	2 x 120	-	555	2 x 120	-	1x120	1 x M12	50
DCS880-S0x-0680-xx	680	2 x 120	-	555	2 x 120	-	1x120	1 x M12	50
DCS880-S0x-0820-xx	820	2 x 150	-	669	2 x 120	-	1x120	1 x M12	50
DCS880-S0x-0900-6/7	900	4 x 95	3 x 150	734	4 x 70	3 x 95	1x150	2 x M12	50
DCS880-S0x-1000-xx	1000	2 x 185	-	816	2 x 150	-	1x150	1 x M12	50

You will find instructions on how to calculate the PE conductor's cross-sectional area in VDE 0100 or in equivalent national standards. We would remind you that power converters may have a current-limiting effect.

Excitation:

Size	H1	H1	H2	H3, H5, H6	H4	
DC output current	6 A	12 A	18 A	25 A	30 A	
max. cross sectional area	6 mm <sup>2</sup> / AWG 10	6 mm <sup>2</sup> / AWG 10	6 mm <sup>2</sup> / AWG 10	6 mm <sup>2</sup> / AWG 10	6 mm <sup>2</sup> / AWG 10	
min. cross sectional area	1 mm <sup>2</sup> / AWG 16	2.5 mm <sup>2</sup> / AWG 13	4 mm <sup>2</sup> / AWG 11	6 mm <sup>2</sup> / AWG 10	6 mm <sup>2</sup> / AWG 10	
Tightening torque	1.5 ... 1.7 Nm					

# Mechanical installation

## Before installation

Install the drive in an upright position with the cooling section facing a wall. Check the installation site according to the requirements below. Refer to chapter *Dimensions and weights* in the Hardware manual for frame details.

### Requirements for the installation site

See chapter *Technical data* in the Hardware manual for the allowed operation conditions of the drive.

#### Wall

The wall should be as close to vertical as possible, of non-flammable material and strong enough to carry the weight of the unit. Check that there is nothing on the wall to inhibit the installation.

#### Floor

The floor or material below the installation should be non-flammable.

#### Free space around the unit

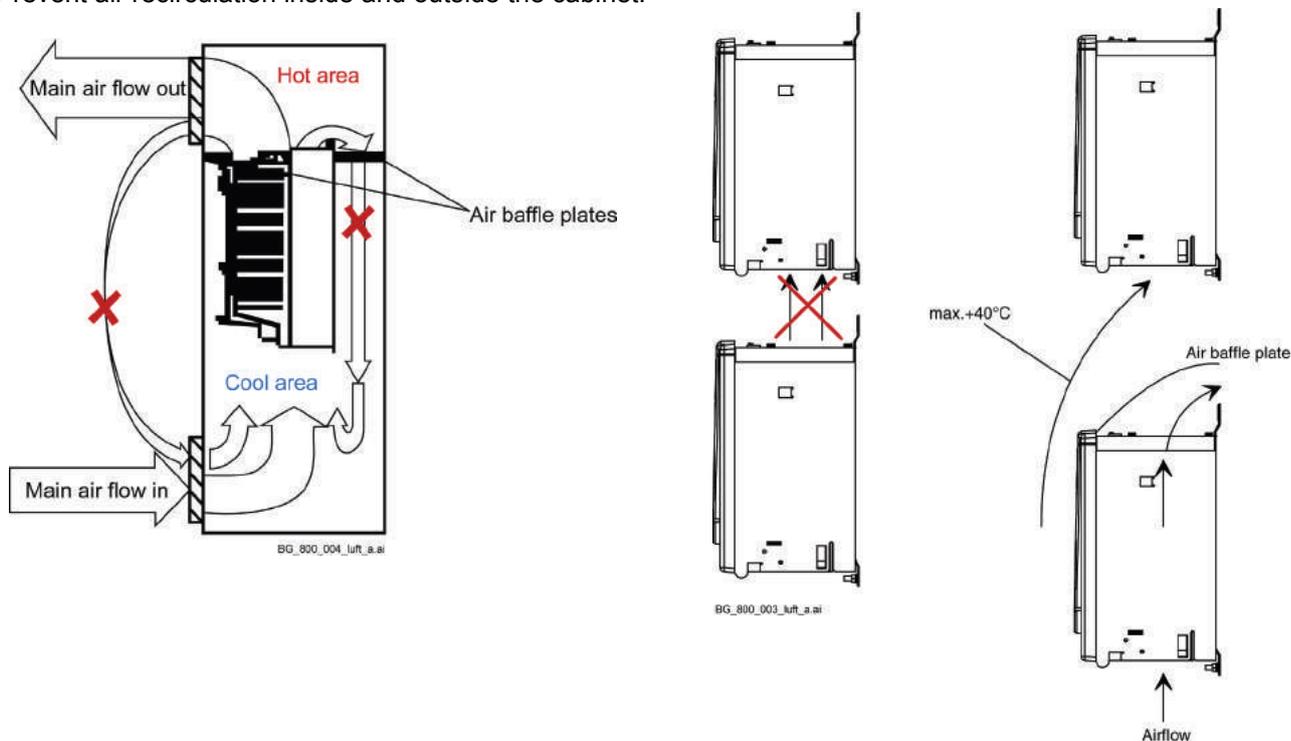
Around the unit free space is required to enable cooling airflow, service and maintenance see chapter *Dimensions and weights* in the Hardware manual.

## Cabinet installation

The required distance between parallel units is five millimetres (0.2 in.) in installations without the front cover. The cooling air entering the unit must not exceed +40 °C (+104 °F).

### Preventing cooling air recirculation Unit above another

Prevent air recirculation inside and outside the cabinet.



Lead the exhaust cooling air away from the unit above. Distances see chapter *Dimensions and weights*.

**Dimensioning and weights**

<b>Size</b>	<b>h * w * d [mm]</b>	<b>h * w * d [inch]</b>	<b>weight [kg]</b>	<b>weight [lbs]</b>
H1	370*270*215	14.56*10.63*8.46	11	25
H2	370*270*271	14.56*10.63*10.67	16	36
H3	460*270*317	18.11*10.63*12.48	25	56
H4	645*270*352	25.39*10.63*13.86	38	84
H5	750*270*372	29.53*10.63*14.65	55	122

# Technical data

## Control circuit terminals on the SDCS-CON-H01

The control circuit terminals are common for all sizes H1 ... H8.

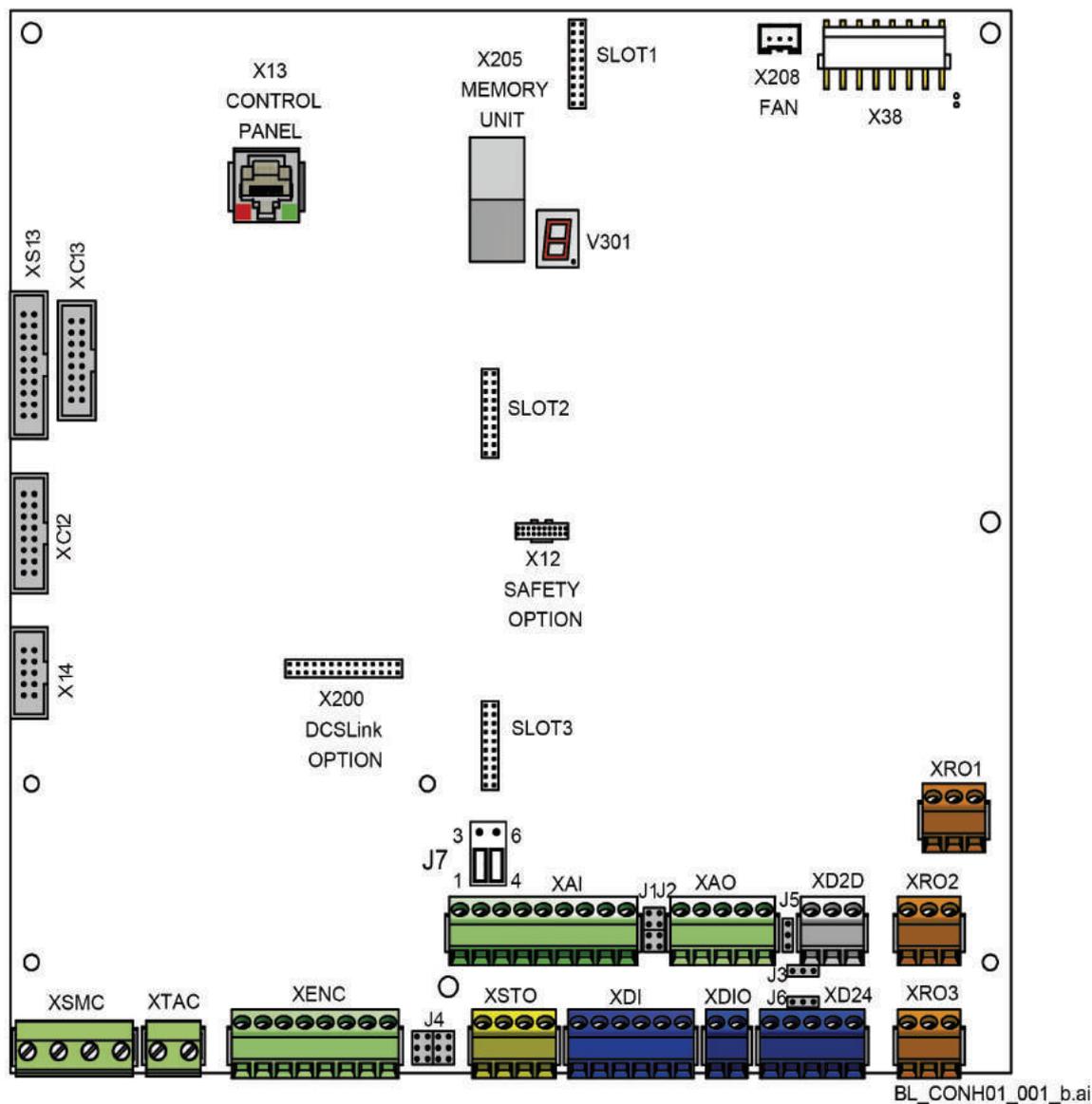
## Location of the control circuit board SDCS-CON-H01

The SDCS-CON-H01 is mounted on an electronic tray. The electronic tray is attached in the housing by means of two hinges.

## Recommended wire size - Tightening torques

Control cables:

Wire sizes:	Tightening torques:
0.5 ... 2.5 mm <sup>2</sup> (24 ... 12 AWG)	0.5 Nm (5 lbf·in) for both stranded and solid wiring



### Control circuit terminal layout

internal 24 V <sub>DC</sub>	External 24 V <sub>DC</sub> used																																																																																																																																																																																																																																																						
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1	MCCOM	250 V <sub>AC</sub> / 30 V <sub>DC</sub> Fixed output for the mains contactor																																																																																																																																																																																																																																																					
2	MCNO	2 A																																																																																																																																																																																																																																																					
3	STOCOM	250 V <sub>AC</sub> / 30 V <sub>DC</sub> Fixed output for safe torque off (STO) zero current monitor																																																																																																																																																																																																																																																					
4	STONO	2 A																																																																																																																																																																																																																																																					
XSTO Safe torque off (STO)																																																																																																																																																																																																																																																							
1	OUT1	24 V <sub>DC</sub> for STO circuit																																																																																																																																																																																																																																																					
2	SGND	Common ground (connected to frame)																																																																																																																																																																																																																																																					
3	IN1	Both circuits must be closed for drive to start																																																																																																																																																																																																																																																					
4	IN2	Open circuits block the firing pulses																																																																																																																																																																																																																																																					
X12	X12	Safety functions module connection																																																																																																																																																																																																																																																					
X13	X13	Control panel connection																																																																																																																																																																																																																																																					
X205	X205	Memory unit connection																																																																																																																																																																																																																																																					
	<p style="text-align: right;">SA_880_010_DCT-PLC_a.ai</p>																																																																																																																																																																																																																																																						
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# Using the control panel

Refer to ACS-AP-x assistant control panels user's manual (3AUA0000085685) for detailed information.

## Basic operation

### What this chapter contains

The chapter describes the basic operations and components of the user interface, lists common user tasks and gives short instructions on how to complete them.

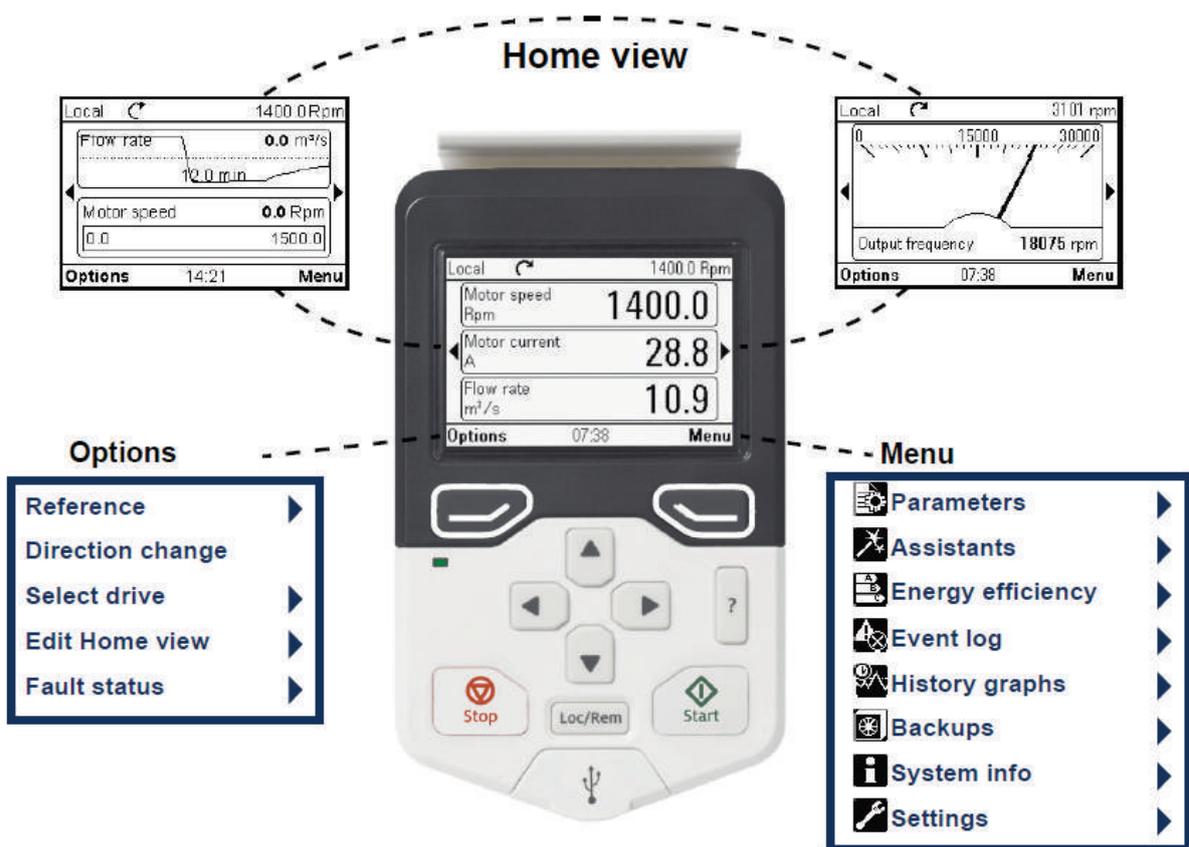
### User interface overview

The user interface has the following main components:

- The Home view through which you can monitor signals.
- The main Menu through which you can access most functions of the control panel. The Menu functions are described in detail in chapter Functions in the main Menu.
- The Options menu through which you can set a reference, select the drive, edit Home view pages, and see the fault and warning status. The Options menu is described in detail in chapter Functions in the Options menu.
- The Help view which provides advice in many situations.
- Faults and warnings view which appear when the drive or the control panel experiences an error.

### Control panel navigation

Use the arrow keys and softkeys for navigation. Follow the choices on the screen.



## Navigation memory

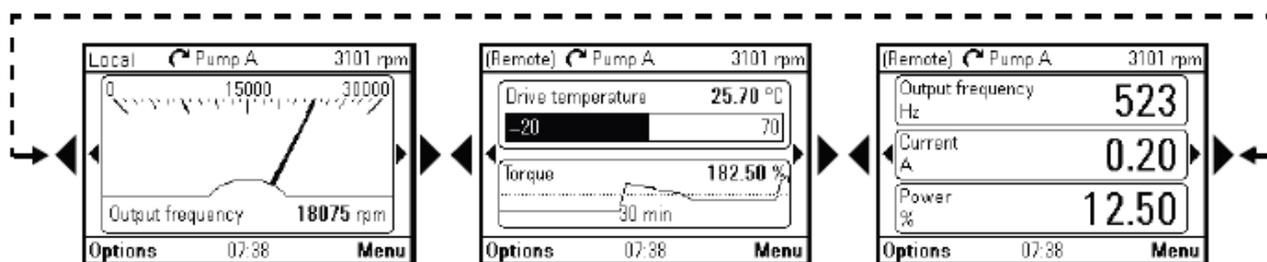
The Assistant control panel has a navigation memory that allows you to backtrack your steps through the user interface with the arrow keys. The path you have last accessed remains in the memory for 10 minutes.

- The left arrow key (◀) moves you backwards in the menu structure. If you press repeatedly, you return back to the Home view.
- The right arrow key (▶) moves you forward in the menu structure. If you press repeatedly, you move forward along the path in the menu structure you had previously accessed.

## Home view

The main view of the control panel is called the Home view. In the Home view, you can monitor the status of the drive, such as its speed, torque or power. The Home view has one or more pages, each of which can display up to three signals.

The number of pages and the signals shown on each page are customizable, and the Home view configuration is saved to the drive whenever you change it. The maximum total number of signals displayed varies from 9 to 21, depending on the drive. In the example below, three Home view pages are used, showing different display formats.



Each application macro and user set has a default Home view configuration. When you select an application macro or restore a user set, the Home view configuration changes accordingly. There is a default Home view configuration in each drive, which can be restored in the Settings menu.

The Home view opens automatically when you power up the drive. The Home view is also displayed from the Options menu or the main Menu if no key is pressed for 10 minutes.

Tip:

You can return to the Home view from any view except special screens by holding down the left softkey .

## Navigating in the Home view

- Use  and  to move between the different pages of the Home view. The page numbers are shown while you scroll between pages.
- Use  or  to adjust the reference (visible in the top right corner).
- Press  to open the main Menu.
- Press  to open the Options menu.

## Help

You can open a context-sensitive help page in all menus and views by pressing .

The help page provides information on the use of the current view or menu, or on possible problems associated with it.

On the help page, you can:

Press  again or  to exit.

## Common user tasks

This following tables list common user tasks and describe how to complete them.

See Functions in the main Menu and Functions in the Options menu for detailed descriptions of functions in the menus.

### Basic operation of the drive

Task	Actions
Start and stop the drive.	In local control, press to start the drive and to stop the drive.
Set the reference (for example, speed) in the Home view.	In local control, go to Options > Reference. Set the reference with the arrow keys.
Switch between local and remote control.	Press REM/LOC

### Parameters

Task	Actions
Choose parameters displayed on the Favorites list.	Go to Menu > Parameters > Favorites > Edit.
View/edit parameters.	Go to Menu > Parameters to view parameters. Move by arrow keys and save using left soft key.
View parameters that differ from Application Macro defaults.	Go to Menu > Parameters > Modified.

### System information and help

Task	Actions
How to get help.	Press to open the context-sensitive help.
View control panel version.	Go to Menu > System info > Control panel.
View drive information.	Go to Menu > System info > Drive.

### Faults and warnings

Task	Actions
Hide/view an active fault.	Faults are automatically displayed. If you hide a fault by pressing (Hide), it automatically reappears after 60 seconds of no key presses. You can also view the fault through Options > Fault status.
Open help page on a fault.	Press to view the help page.
Reset an active fault.	Press (Reset) to reset an active fault.
View tripping faults.	Go to Menu > Event log > Primary faults.
Hide/view an active warning.	Warnings are automatically displayed. If you hide a warning by pressing (Hide), it automatically reappears if the warning is still active after 60 seconds of no key presses.
Open help page on a warning.	Press (How to fix) or to view the help page.
Reset an active warning.	Warnings disappear automatically once the condition that has triggered it goes away.
View past warnings and faults.	Go to Menu > Event log > Other events.

### Basic settings and assistants

Task	Actions
Change language.	Go to Menu > Settings > Language.
Change time and date, and related settings.	Go to Menu > Settings > Date & time.
Launch an assistant.	Go to Menu > Assistants and select an assistant to launch.

### Backups

Task	Actions
Create a backup.	Creates an backup of firmware parameters to the panel.
Restore a backup.	Restores a backup to the firmware parameters of DCT880. It is mandatory to set the unit in local mode before.

## DCS880 Set up control panel assistant

### General display features

Following modes are available in the MAIN MENU:

1. Parameters mode
2. Start-up assistants mode
  - a. Name plate data
  - b. Autotuning field current controller
  - c. Autotuning armature current controller
  - d. First motor tuning
  - e. Speed feedback assistant  
(Tacho fine tuning not available)
  - f. Autotuning speed controller
  - g. Field weakening assistant  
(only used when maximum speed is higher than base speed)
  - h. Make a back up

### Parameters entered by assistant

99.07	M1 used field exciter type
99.10	Nominal mains voltage
99.11	M1 nominal current
99.12	M1 nominal voltage
99.13	M1 nominal field current
99.14	M1 nominal base speed
30.11	M1 minimum speed
30.12	M1 maximum speed
30.19	Minimum torque 1
30.20	Maximum torque 1
30.35	M1 current limit bridge 1
30.34	M1 current limit bridge 2
31.30	M1 overspeed trip margin
31.44	Armature overcurrent level
94.23	OnBoard encoder pulses/revolution
94.24	OnBoard encoder type
94.25	OnBoard encoder speed calc type
94.07	M1 tacho type
94.08	M1 tacho voltage at 1000 rmp
90.41	M1 feedback selection
23.12	Acceleration time 1
23.13	Deceleration time 1
31.58	M1 field current low level
28.17	M1 EMF/field control mode

# Set UP Procedure

Follow the procedure below for setting up the thyristor power controller

## Checking prior to powering On

Check the following before powering on the thyristor power controller

- (1) Check the wiring to the input terminals U1, V1 and W1 and output terminals U2, V2 and W2. Also check that the grounding wires are connected to the grounding terminals (PE).



### **WARNING!**

Be sure to connect the grounding wires of the power controller to the ground electrodes. Otherwise, an electric shock could occur.

---

- (2) Check the wiring to the aux. voltage supply.
- (3) Check the wiring to neutral point connection for single phase or 3ph + neutral configurations connected to XN1 : 1
- (4) Check the control circuit terminals and main circuit terminals for short circuit or ground faults.
- (5) Check for loose terminals, connectors and screws.
- (6) Make sure that all switches of devices connected to the power controller are turned OFF.  
Power on the power controller with any of those switches being ON may cause unexpected behavior at load side.

## Power ON and check



### **WARNING!**

Be sure to mount the front cover before turning the power ON. Do not remove the cover when the power controller is ON.  
Do not operate switches with wet hands.  
Otherwise, an electric shock could occur.

---

Turn the aux. power ON and check the following points. The following is a case when no parameter data is changed from factory defaults.

- (1) Check that the assistant control panel displays no fault and set date and time
- (2) Check that the used analog and digital inputs work properly
  - Check signals 12.11, 12.21 and 12.31 for analog inputs
  - Check signals 10.1 for digital inputs
  - Set the inputs from voltage to current if needed

Turn on the input power and check the following points.

- (1) Check following parameters
  - a. In case of three phase system supply
    - Voltage between input phases
    - signals 1.07, 1.08, 1.09
  - b. In case of single phase system supply
    - Voltage between phase and neutral
    - signals 1.01, 1.02, 1.03

## PC-tool “Drive composer entry”

Drive composer entry is a free of charge startup and maintenance PC tool for ABB's common architecture industrial devices series such as ACS880, DCT880 etc.

The key functions of Drive composer entry are the following:

- Connect point-to-point to one DCS880 or DCT880 using Assistant control panel's USB port
- Show the actual status of the connected DCS880 or DCT880
- View, edit on line and search the parameters
- Show modified parameters (not at default)
- Print parameters
- Save parameters from Drive to PC and download parameters from PC to Drive
- Monitor drive signals graphically and numerically (Limited functionality)
- Local Control of a Drive
- Use of workspace and customized parameter windows
- Show event logger (faults and warnings)

Download the software from the internet: [www.abb.com](http://www.abb.com) → Search for Drive composer

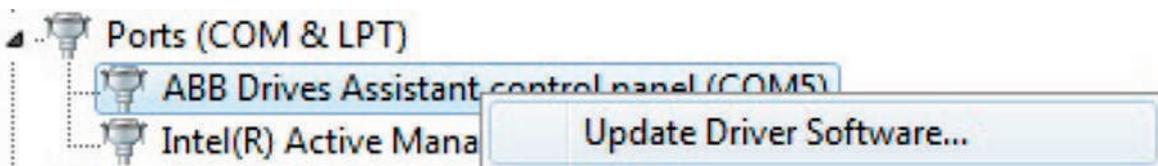
Unzip the **Drive\_composer\_entry.zip** file

Start the installation program **Setup.exe** of Drive composer entry and follow the instruction carefully

Connect the panel to your PC

Install the second part of drivers manually as follows

In the **Start** menu of your computer, enter *Device manager* in the search field and click **Device Manager**



Click **Browse my computer for driver software** to search the driver software

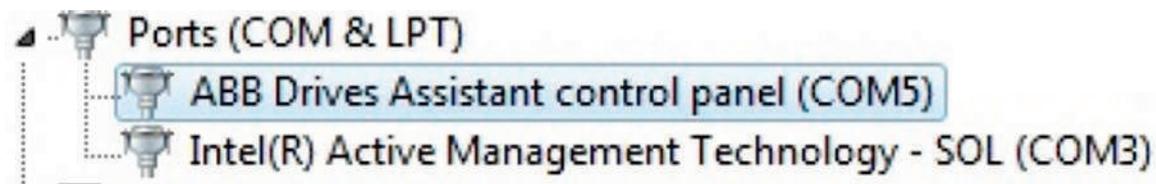
Local Disk (C:) ▶ Program Files (x86) ▶ DriveWare ▶ Drive composer entry ▶ PanelDriver

Click **Browse** to locate the drivers and click **Next**.

In the **Windows Security** window, click **Install** to install the device software

After installation is complete, click **Close**.

The Driver software for the device is installed at given COM port



First time connect the PC-tool to the Drive

1. Connect your PC to the Assistant control panel with a USB cable.

The following text appears on the Assistant control panel screen: "USB connected".

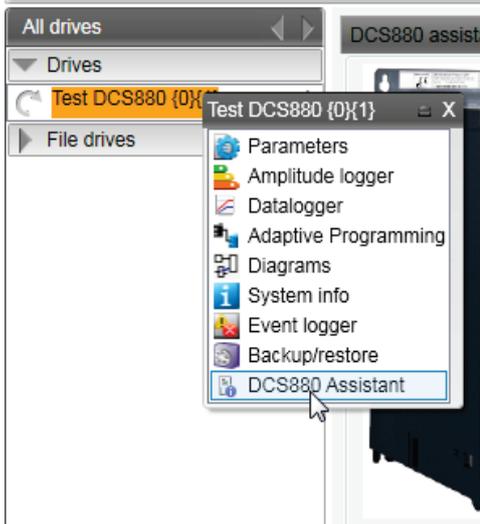
**Note:** The Assistant control panel cannot be used when it is connected to a PC.

2. Launch Drive composer by double-clicking **Drive composer entry.exe**
3. Select the COM port that your Assistant control panel is using.

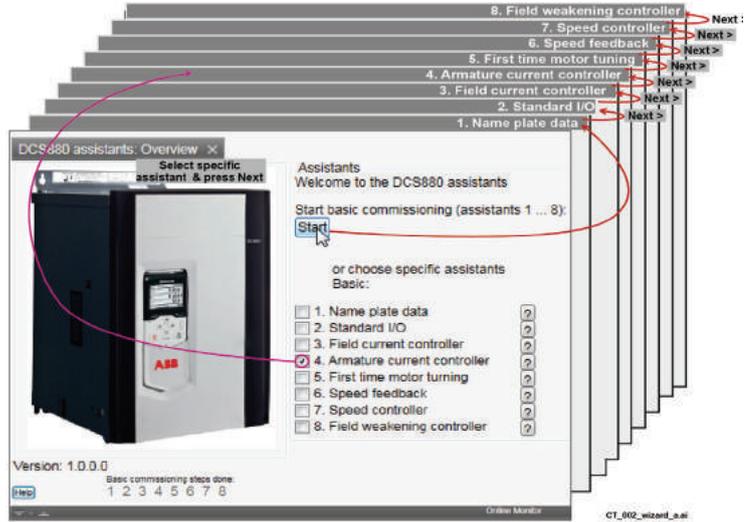
This question is asked only when the program is launched for the first time. If you want to change the COM port settings, go to **View** → **Settings** in Drive composer.

# Drive composer pro DCS880 assistant

Start the wizard in drive composer



For basic commissioning press the *Start* button or select a specific assistant:



For more information about the drive composer, parameters, faults and alarms press the *Help* button!

# Parameters

## What this chapter contains

The chapter describes the parameters and signals of the firmware.

## Terms and abbreviations

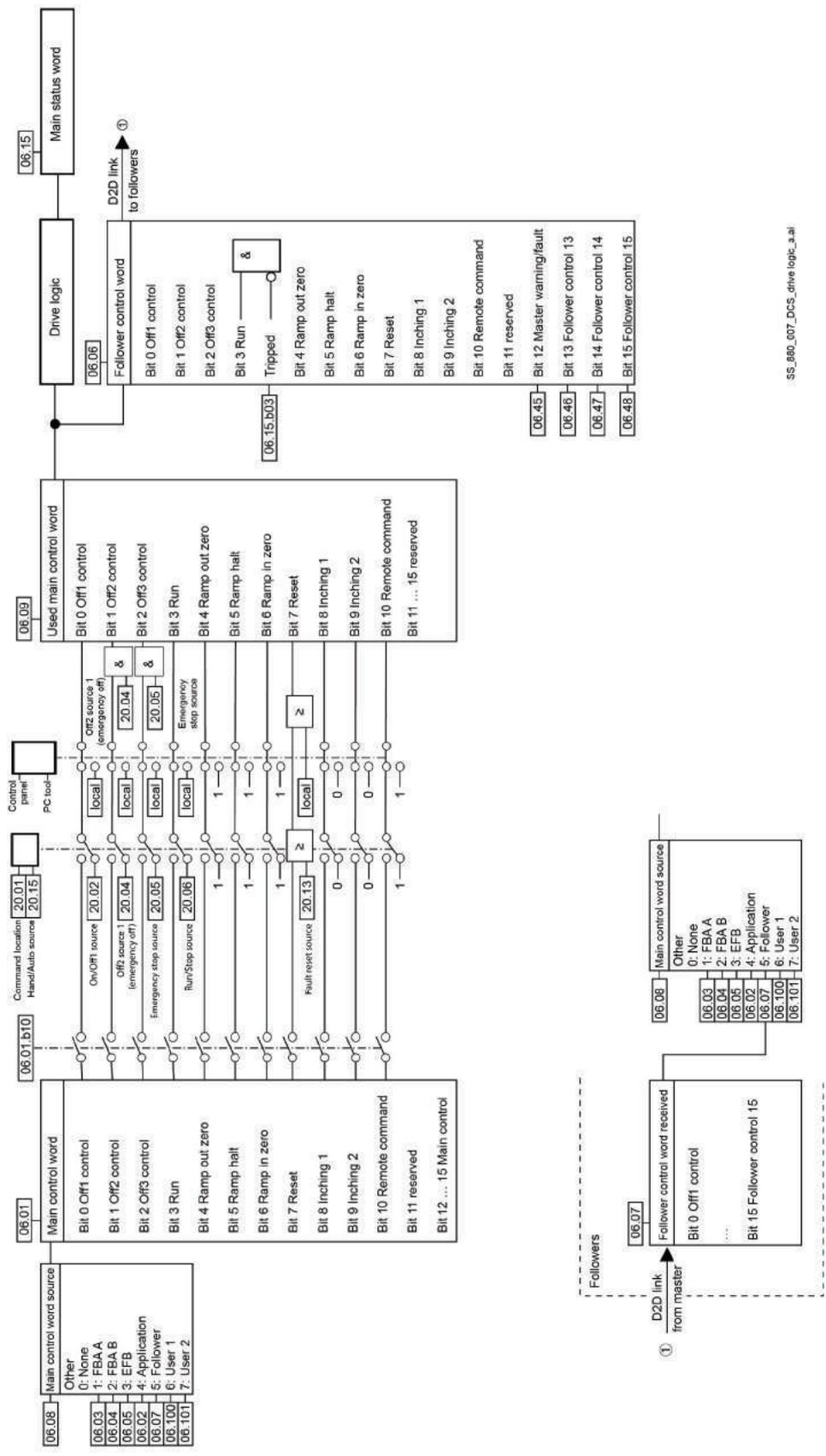
Term	Definition
Signal	Type of parameter that is the result of a measurement or calculation by the drive, or contains status information. Most signals are read-only, but some (especially counter-type signals) can be reset.
Default (def.)	The default value of a parameter.
Scale/Fbeq16	16-bit fieldbus equivalent: The scaling between the value shown on the panel and the integer used in communication when a 16-bit value is selected for transmission to an external system. A dash (-) indicates that the parameter is not accessible in 16-bit format.
Other	The value is taken from another parameter. Choosing "Other" displays a parameter list in which the user can specify the source parameter.
Other [bit]	The value is taken from a specific bit in another parameter. Choosing "Other" displays a parameter list in which the user can specify the source parameter and bit.
Parameter	A user-adjustable operating instruction for the drive.
p.u.	Per unit

## Summary of parameter groups

Group	Contents
<a href="#">01 Actual values</a>	Basic signals for monitoring the drive.
<a href="#">03 Input references</a>	Values of references received from various sources.
<a href="#">04 Warnings and faults</a>	Information on warnings and faults that occurred last. For explanations of individual warning and fault codes.
<a href="#">05 Diagnostics</a>	Various run-time-type counters and measurements related to drive maintenance.
<a href="#">06 Control and status words</a>	Drive control, status and event words.
<a href="#">07 System info</a>	The drive's hardware and firmware information.
<a href="#">10 Standard DI, RO</a>	Configuration of digital inputs and relay outputs.
<a href="#">11 Standard DIO, FI, FO</a>	Configuration of digital input/outputs and frequency inputs/outputs.
<a href="#">12 Standard AI</a>	Configuration of standard analog inputs.
<a href="#">13 Standard AO</a>	Configuration of standard analog outputs.
<a href="#">14 I/O extension module 1</a>	Configuration of I/O extension module 1.
<a href="#">15 I/O extension module 2</a>	Configuration of I/O extension module 2.
<a href="#">16 I/O extension module 3</a>	Configuration of I/O extension module 3.
<a href="#">19 I/O Operation mode</a>	Selection of local and external control locations and operating modes.
<a href="#">20 Start/Stop/Direction</a>	Start/Stop/Direction and run/start/jog enable signal source selection. Positive/Negative reference enable source selection. Breaker and acknowledge source selection.
<a href="#">21 Start/Stop mode</a>	Start and stop modes, emergency stop mode and zero speed.
<a href="#">22 Speed reference selection</a>	Speed reference selection and motor potentiometer settings.
<a href="#">23 Speed reference ramp</a>	Speed reference ramp settings (programming of the acceleration and deceleration rates for the drive).
<a href="#">24 Speed reference conditioning</a>	Speed error calculation, speed error window control configuration and speed error ( $\Delta n$ ) step.
<a href="#">25 Speed control</a>	Speed controller settings.
<a href="#">26 Torque reference chain</a>	Settings for the torque reference chain.
<a href="#">27 Armature current control</a>	Settings for the armature current control chain.
<a href="#">28 EMF and field current control</a>	Settings for the EMF and field current control chain.
<a href="#">29 12-pulse/Hardparallel</a>	Settings for 12-pulse and hardparallel.
<a href="#">30 Control limits</a>	Drive operation limits.

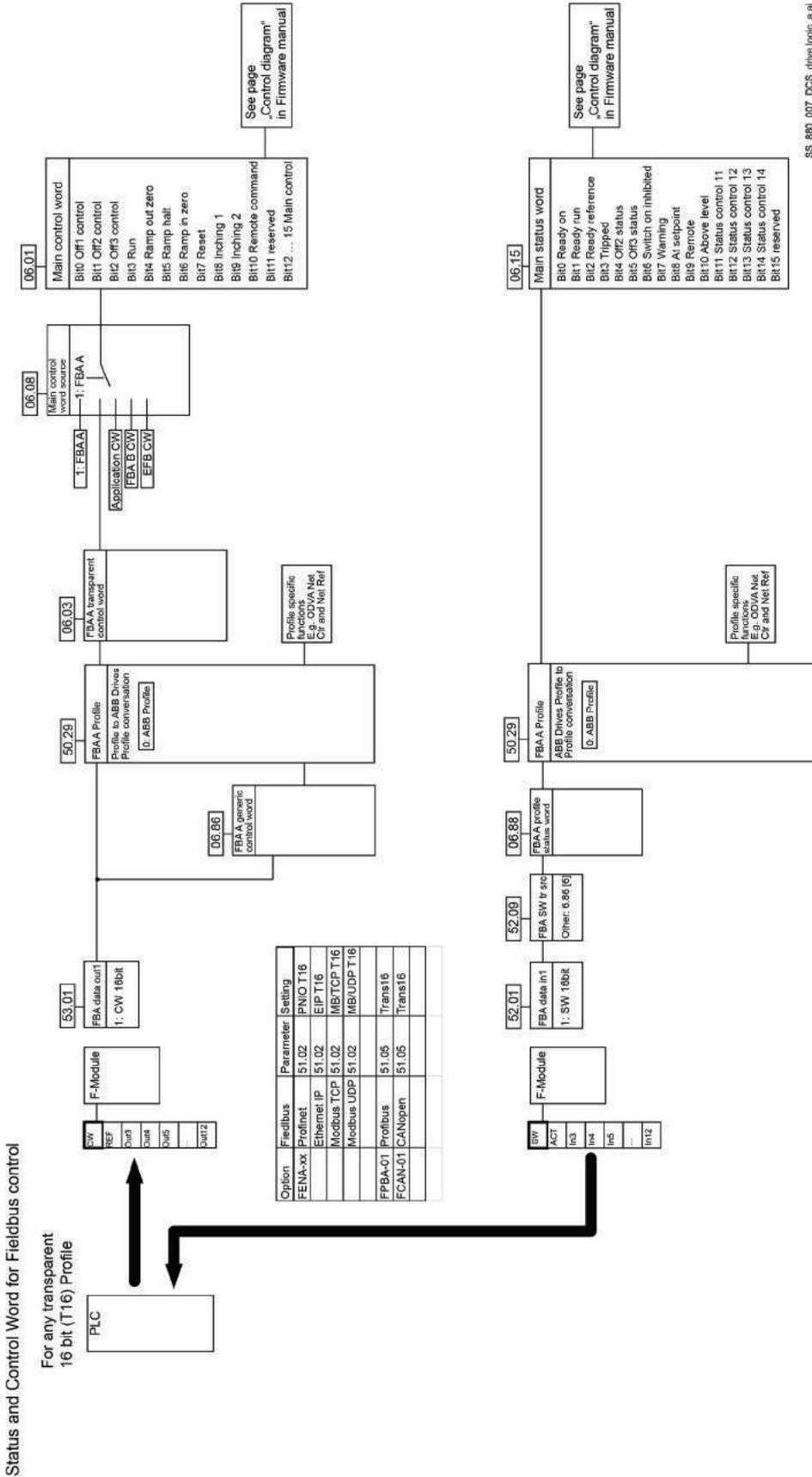
<a href="#"><u>31 Fault functions and fault levels</u></a>	Configuration of external events. Selection of the drive behavior in fault situations.
<a href="#"><u>32 Supervision</u></a>	Configuration of signal supervision functions 1 ... 3. Three values can be monitored. A warning or fault is generated whenever predefined limits are exceeded.
<a href="#"><u>33 Generic timer &amp; counter</u></a>	Configuration of maintenance timers/counters.
<a href="#"><u>35 Motor thermal protection</u></a>	Motor thermal protection settings such as temperature measurement configuration and load curve definition.
<a href="#"><u>36 Load analyzer</u></a>	Peak value and amplitude logger settings.
<a href="#"><u>37 User load curve</u></a>	Settings for user load curve.
<a href="#"><u>40 Process PID</u></a>	Parameter values for process PID controller.
<a href="#"><u>42 Shared motion (2nd motor)</u></a>	Configuration of 2 <sup>nd</sup> motor.
<a href="#"><u>44 Mechanical brake control</u></a>	Configuration of mechanical brake.
<a href="#"><u>45 Energy efficiency</u></a>	Settings for the energy saving calculators.
<a href="#"><u>46 Monitoring/Scaling settings</u></a>	Speed supervision settings, signal filtering and general scaling settings.
<a href="#"><u>47 Data storage</u></a>	Data storage parameters that can be written to and read from using other parameters' source and target settings.
<a href="#"><u>49 Panel port communication</u></a>	Communication settings for the control panel port on the drive.
<a href="#"><u>50 Fieldbus adapter (FBA)!</u></a>	Fieldbus communication configuration.
<a href="#"><u>51 FBA A settings</u></a>	Fieldbus adapter A configuration.
<a href="#"><u>52 FBA A data in</u></a>	Selection of data sent by fieldbus adapter A to the master (e.g. PLC).
<a href="#"><u>53 FBA A data out</u></a>	Selection of data sent by the master (e.g. PLC) to fieldbus adapter A.
<a href="#"><u>54 FBA B settings</u></a>	Description see group 51 FBA A settings.
<a href="#"><u>55 FBA B data in</u></a>	Description see group 52 FBA A data in.
<a href="#"><u>56 FBA B data out</u></a>	Description see group 53 FBA A data out.
<a href="#"><u>58 Embedded fieldbus</u></a>	Embedded fieldbus (EFB) configuration.
<a href="#"><u>60 DDCS Communication</u></a>	DDCS communication configuration.
<a href="#"><u>61 D2D and DDCS transmit data</u></a>	Defines the data sent from the drive to the DDCS/D2D link.
<a href="#"><u>62 D2D and DDCS receive data</u></a>	Defines the data sent from the DDCS/D2D link to the drive.
<a href="#"><u>70 DCSTLink Communication</u></a>	Defines the DCSTLink communication.
<a href="#"><u>74 ... 89 Application specific groups</u></a>	Groups used for application programming.
<a href="#"><u>90 Feedback selection</u></a>	Motor and load feedback configuration.
<a href="#"><u>91 Encoder module settings</u></a>	Configuration of the encoder interface modules.
<a href="#"><u>92 Encoder 1 configuration</u></a>	Settings for encoder 1.
<a href="#"><u>93 Encoder 2 configuration</u></a>	Settings for encoder 2.
<a href="#"><u>94 OnBoard speed feedback configuration</u></a>	Settings for analog tacho and OnBoard encoder.
<a href="#"><u>95 HW configuration</u></a>	Various hardware-related settings.
<a href="#"><u>96 System</u></a>	Language selection; access levels; macro selection; parameter save and restore; control board reboot; user parameter sets; unit selection; data logger triggering; parameter checksum calculation; user lock.
<a href="#"><u>99 Motor data</u></a>	Motor configuration settings.

# Drive logic

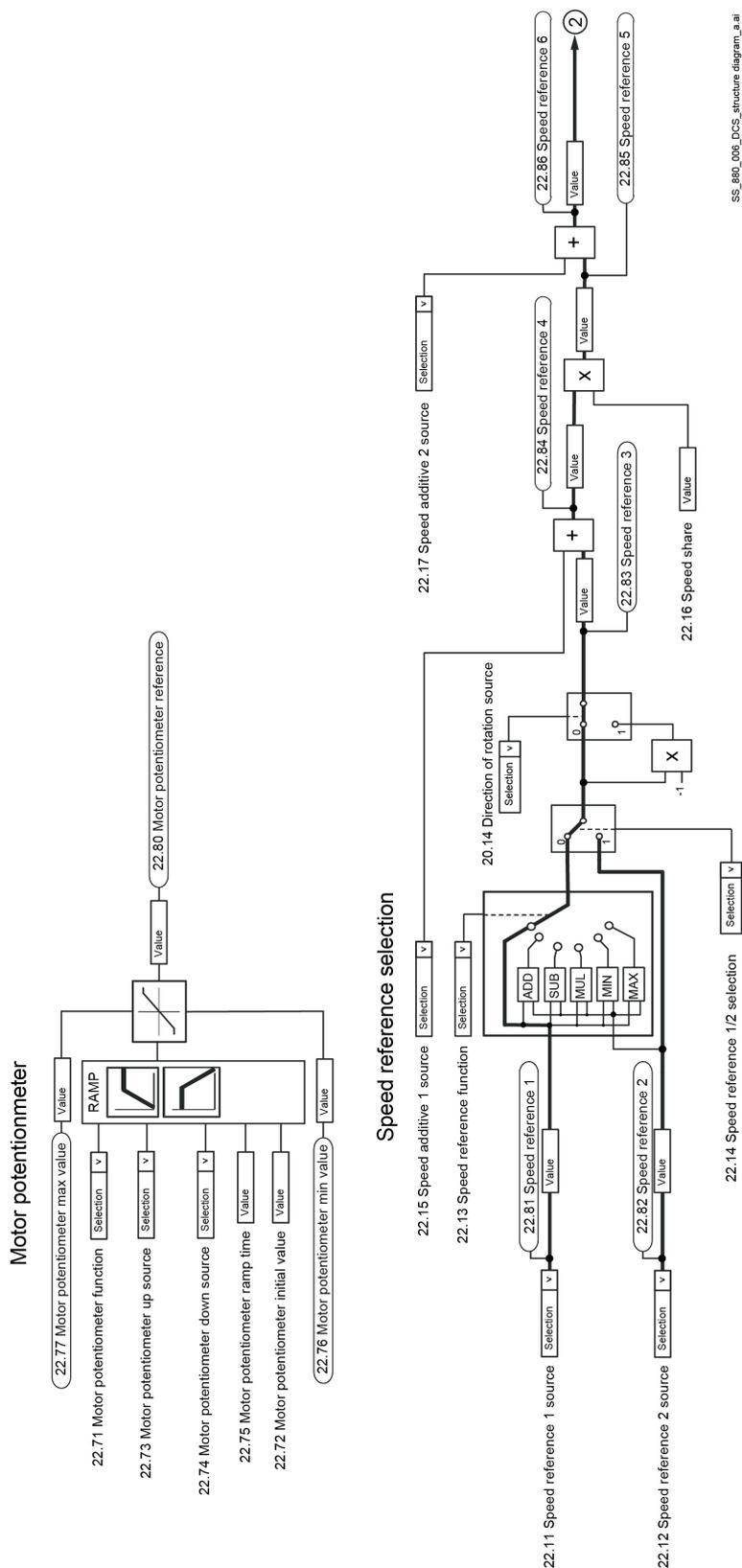


SS\_880\_007\_DCS\_drive\_logic\_a.ai

# Fieldbus control



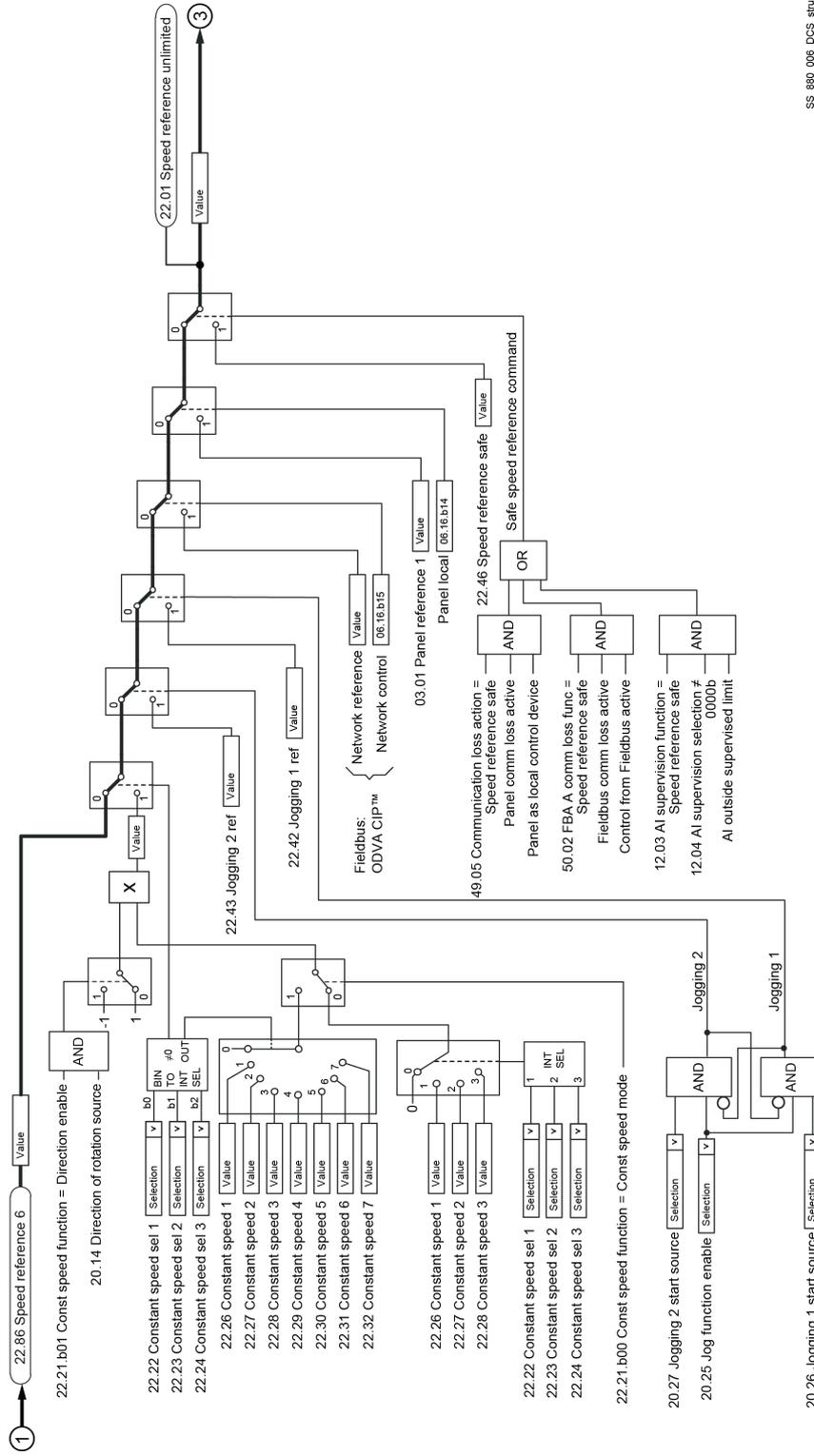
# Firmware structure diagrams



SS\_880\_006\_DCS\_structure\_diagram\_s.ai

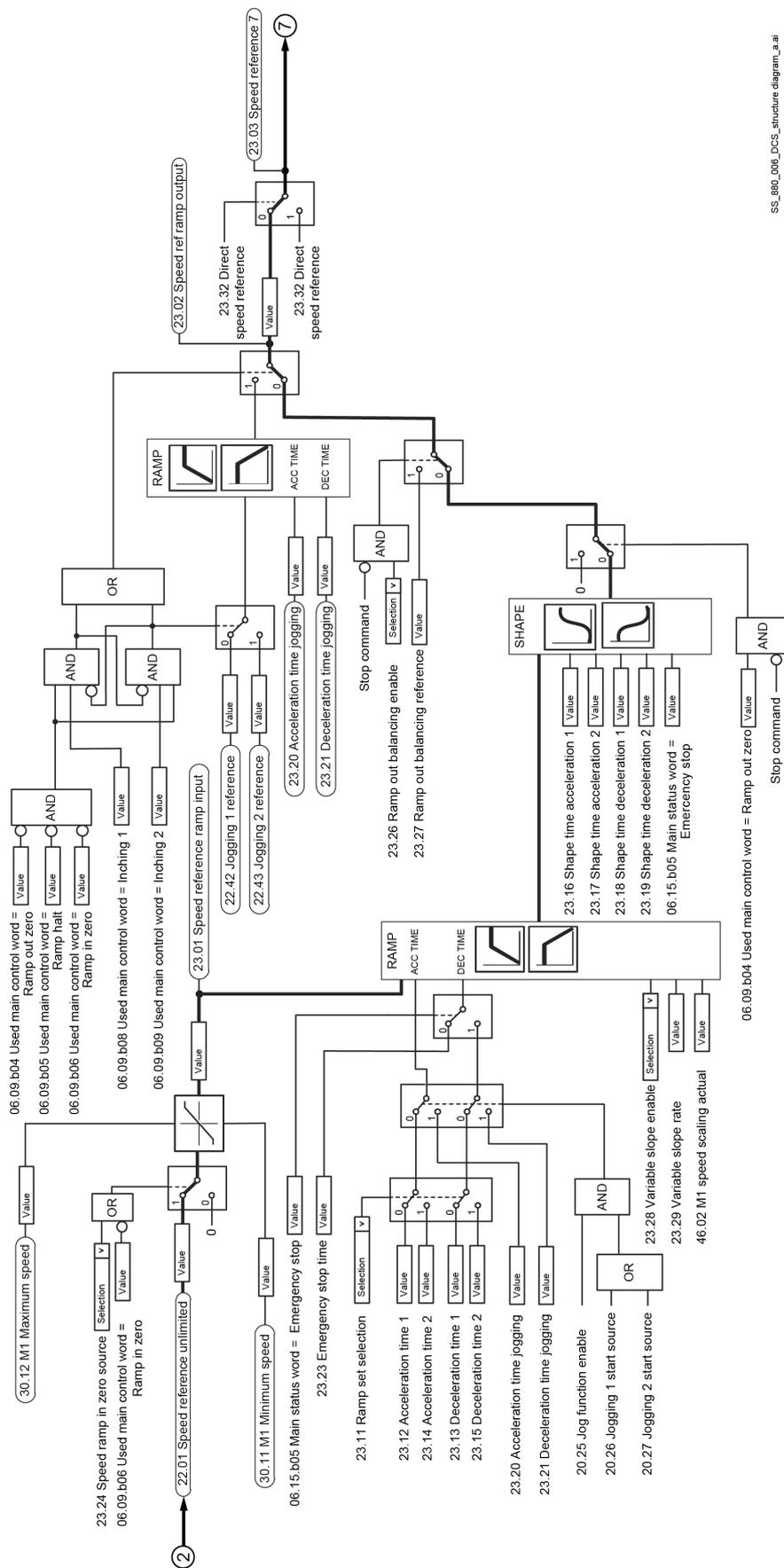
1

Jogging, constant speed references and speed reference chain

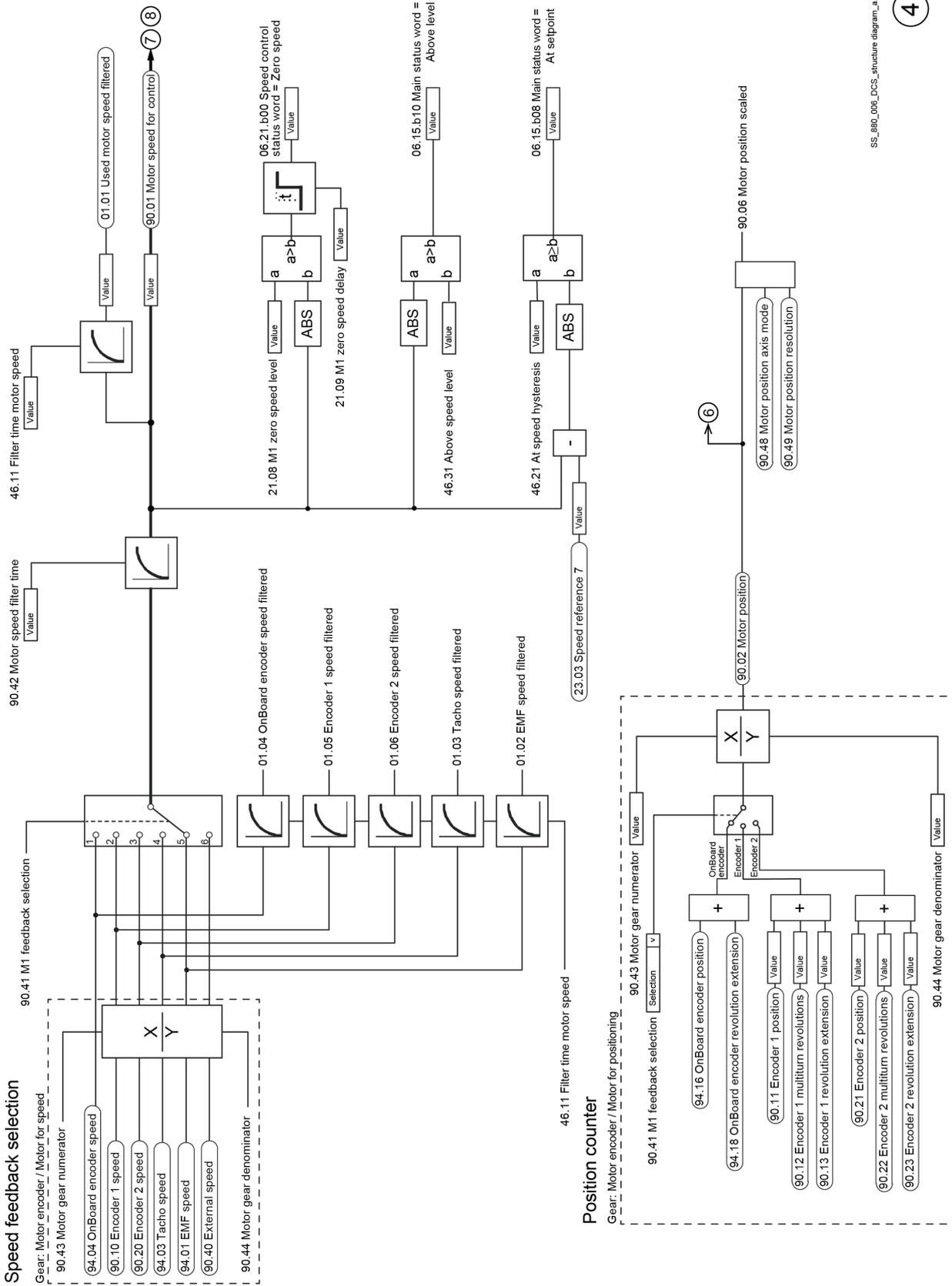


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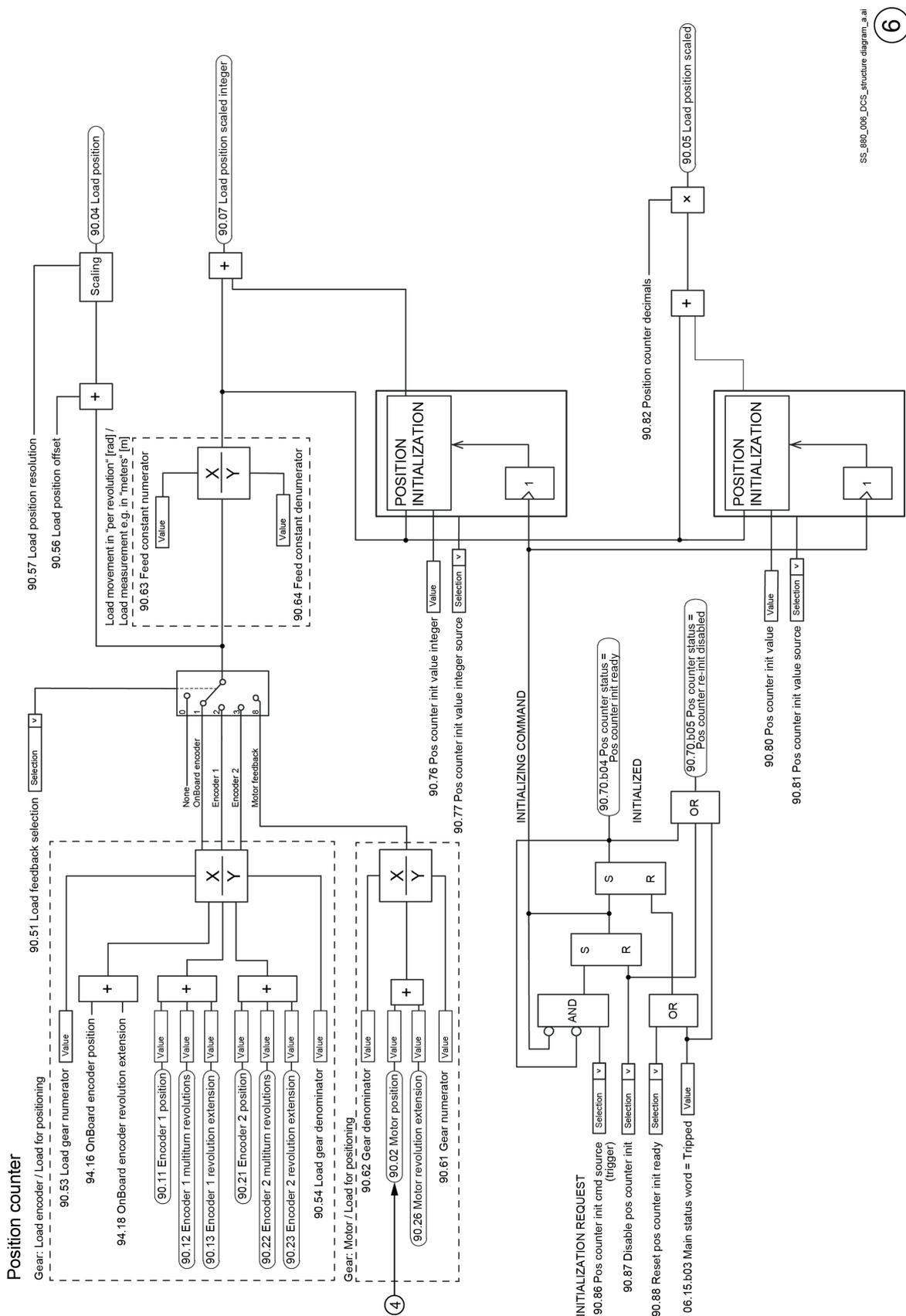
Speed reference ramp and shaping



SS\_880\_006\_DCS\_structure\_diagram\_a.ai

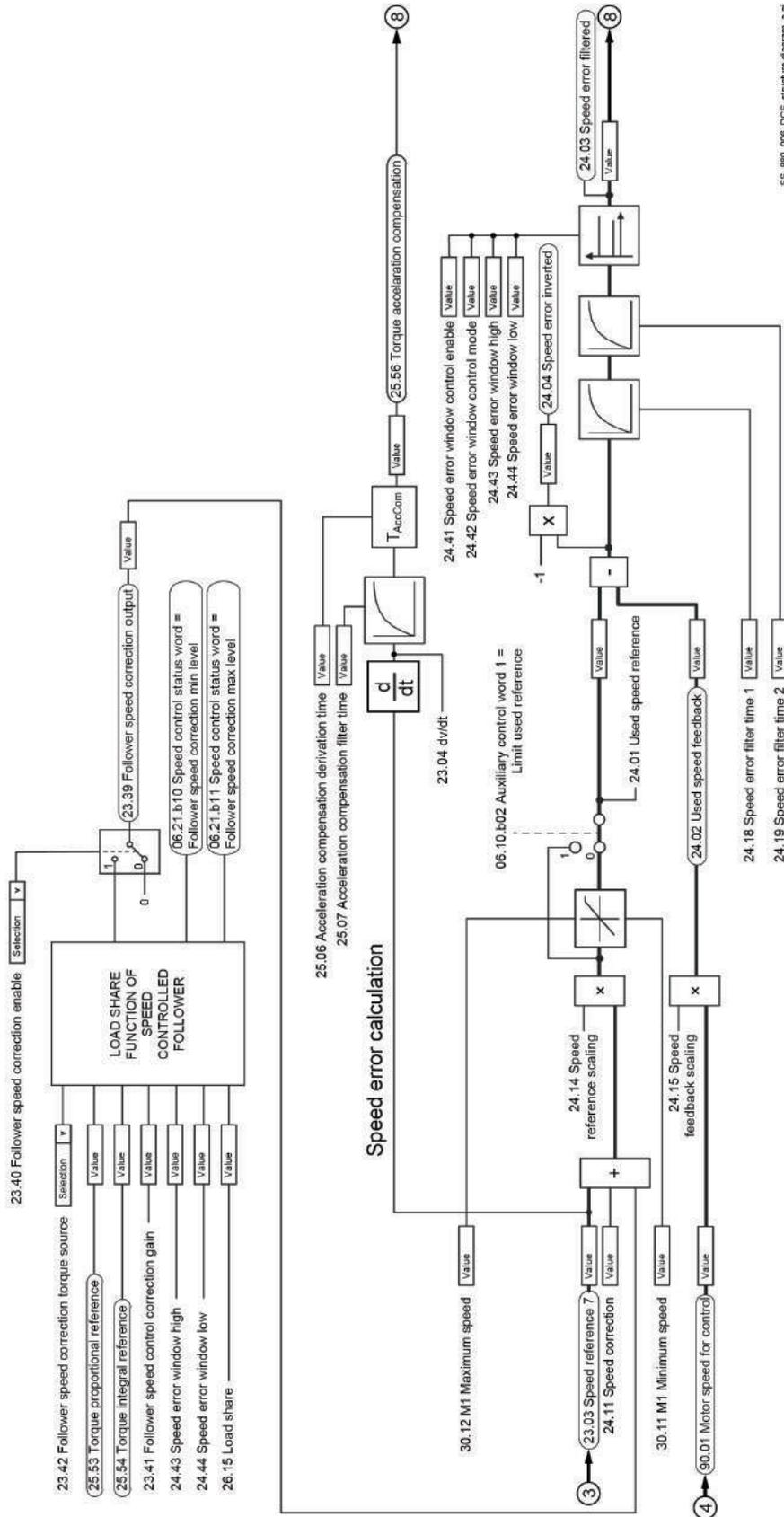


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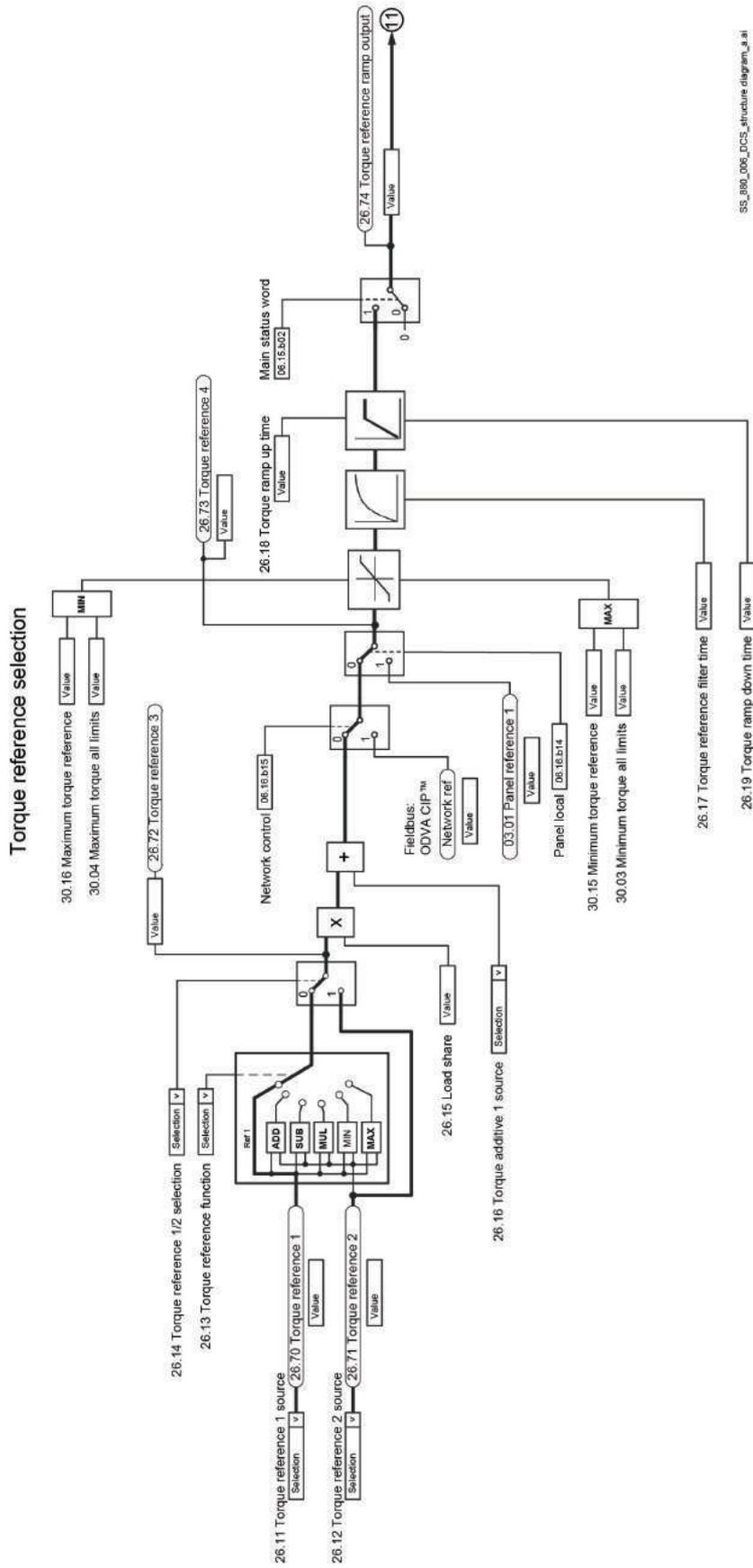
SS\_880\_006\_DCS\_structure diagram\_a.ai **6**

Follower load share



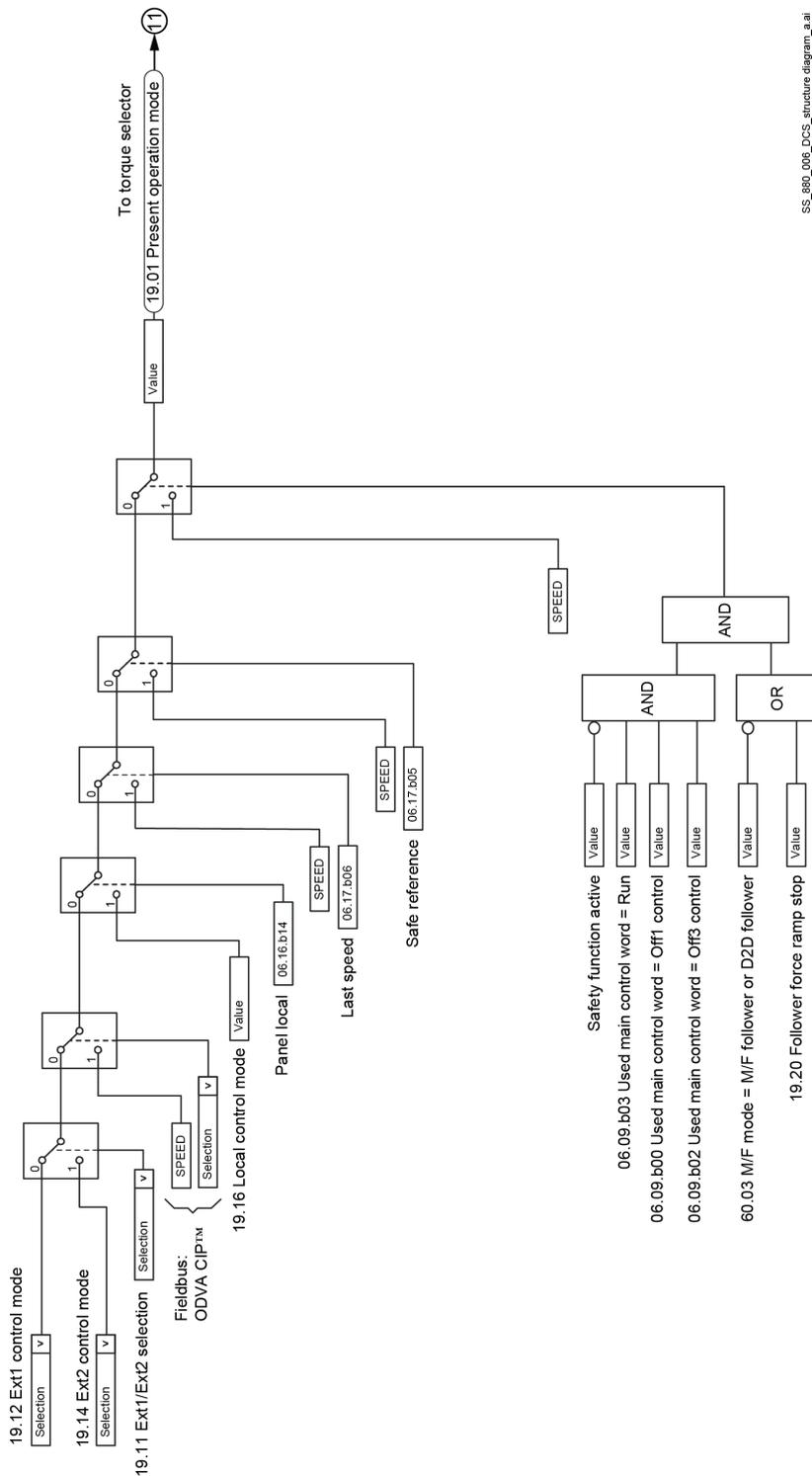
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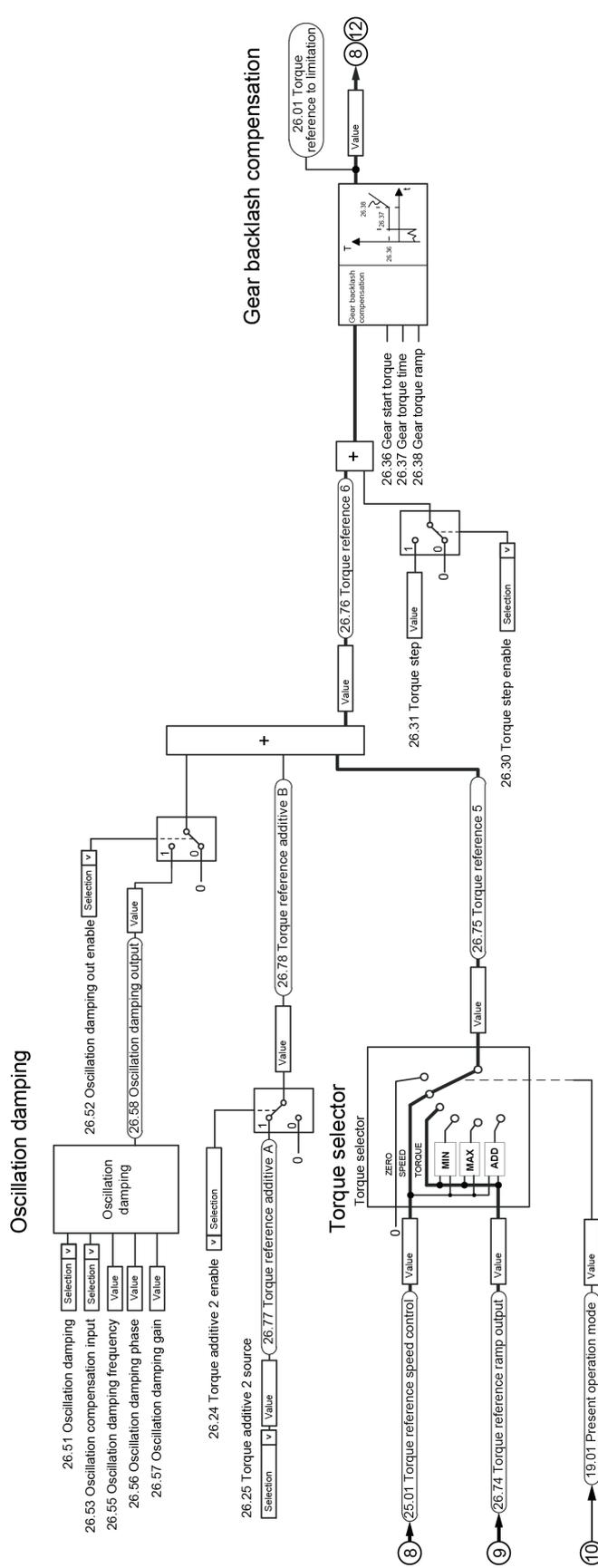


55\_880\_006\_DCS\_4inches diagram\_a.ai

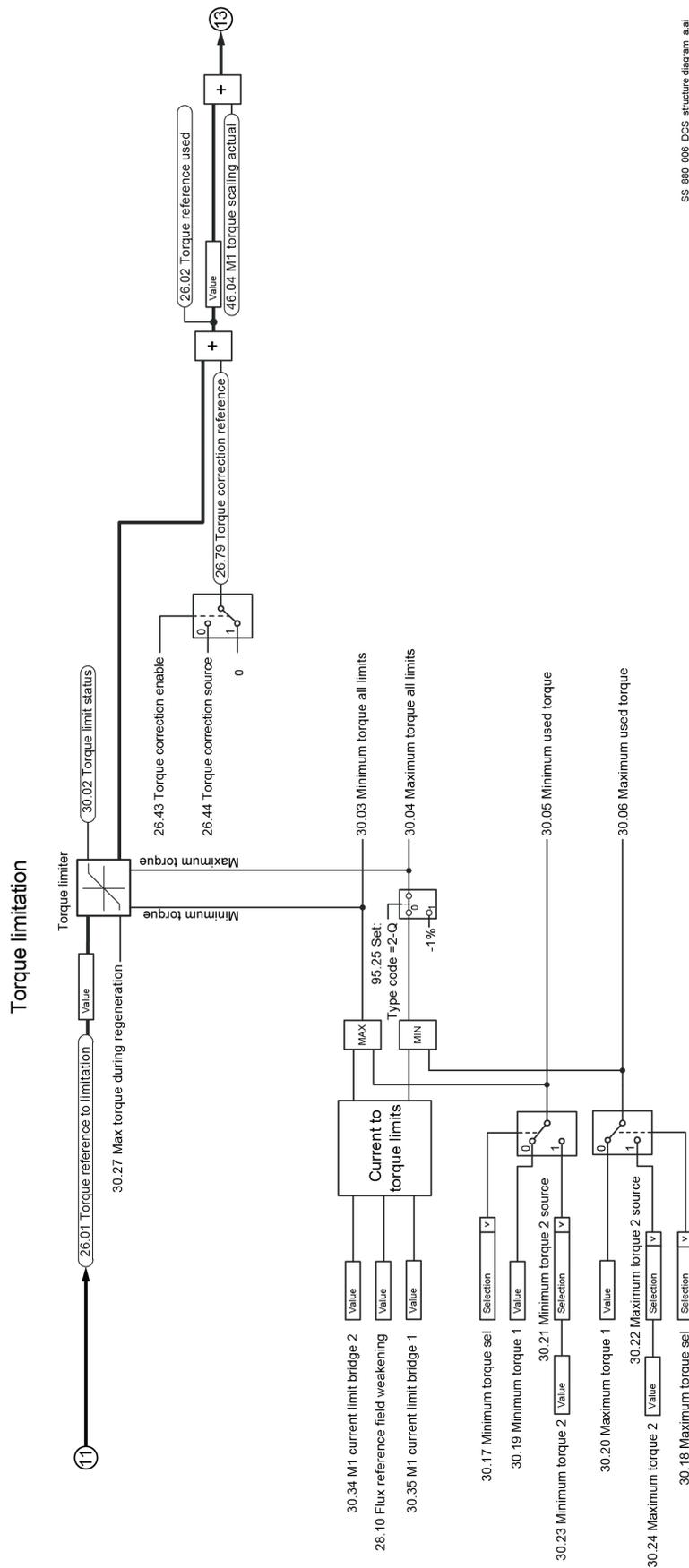
Control mode selection



SS\_880\_006\_DCS\_structure\_diagram\_a.ai



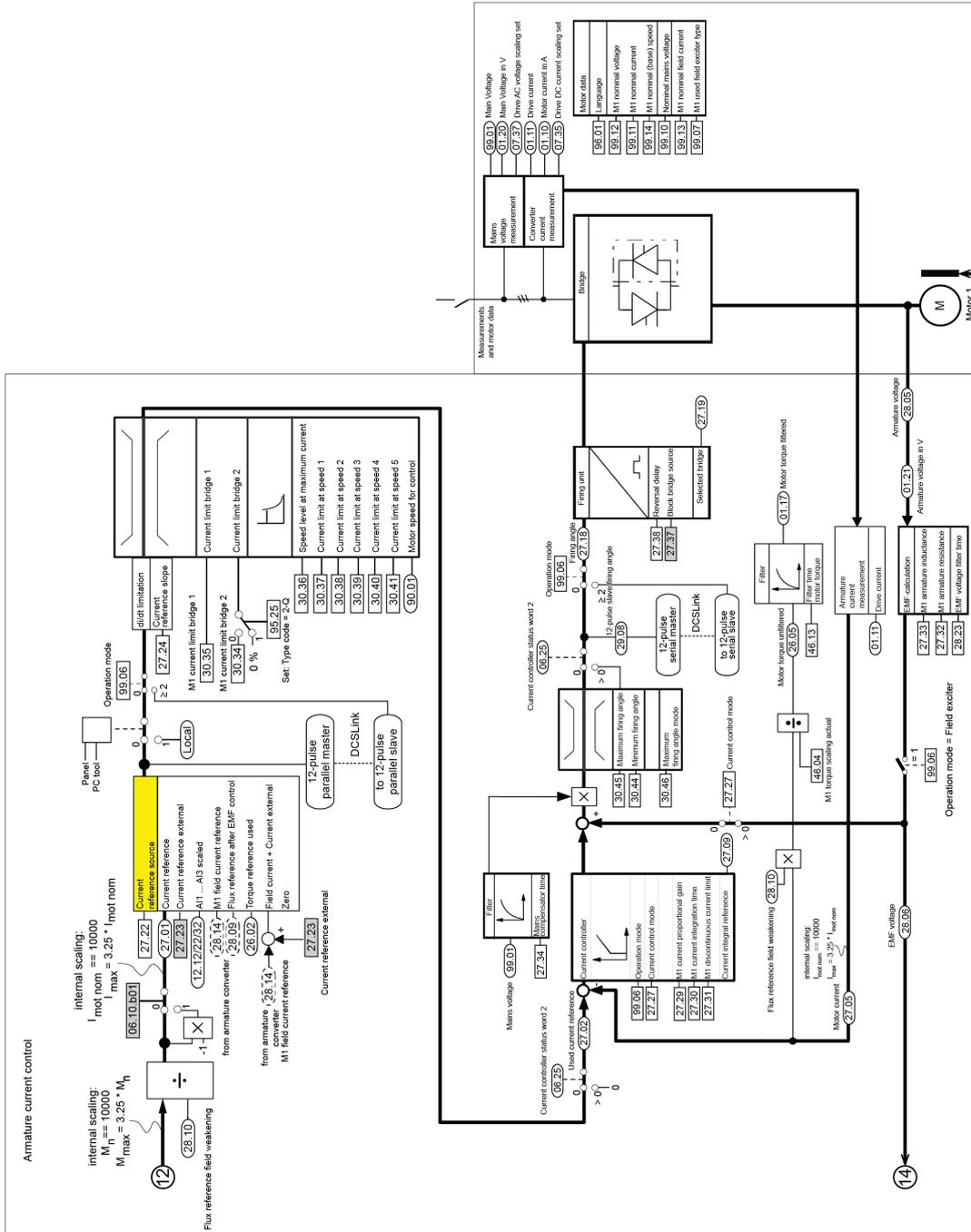
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SS\_880\_006\_DCS\_structure\_diagram\_a.ai

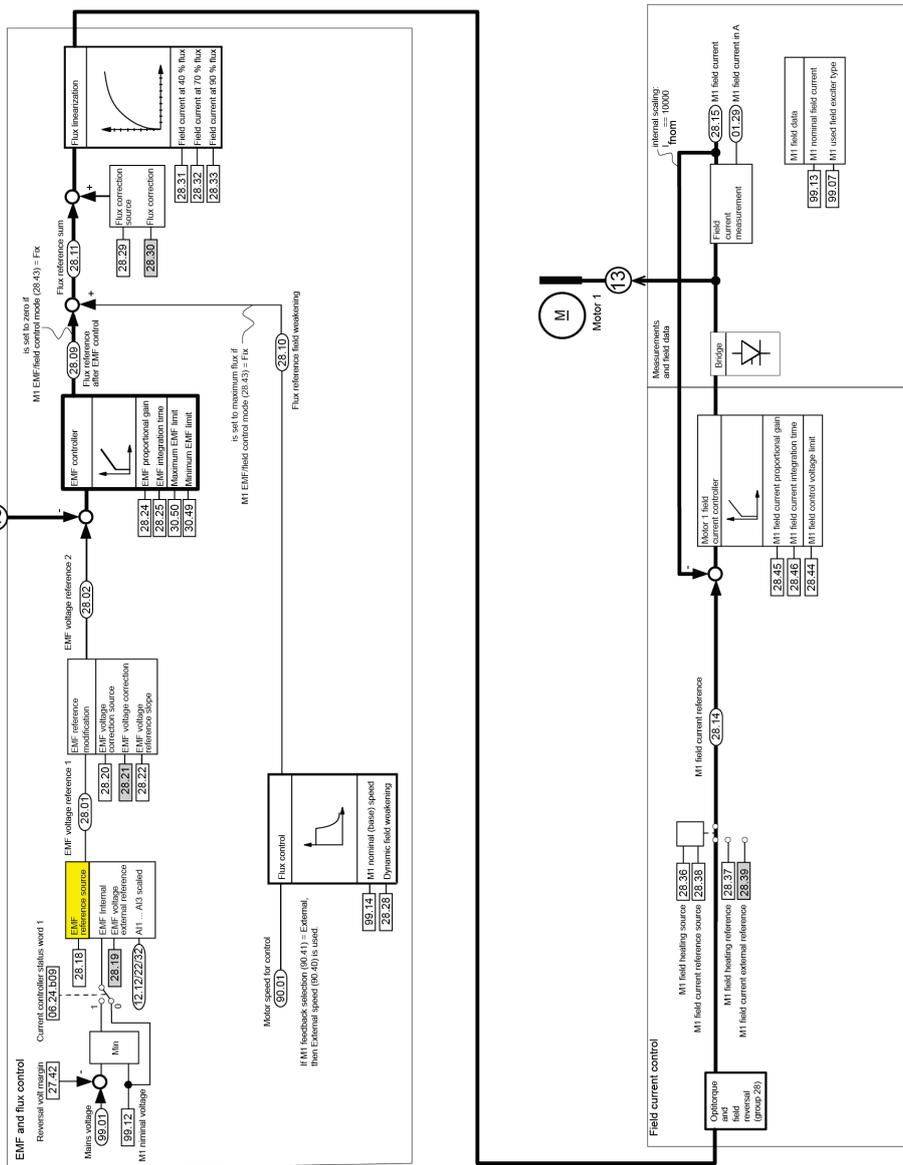
12

Armature current control



SS\_880\_006\_DCS\_structure diagram\_a\_i

Field current control (one field exciter)



SS\_890\_006\_DCS\_structure diagram\_a.ai







## Declaration of Conformity

( Directive 2011/65/EU [RoHS II Directive] )

Document code: 3ADW000483R0101

We, ABB Automation Products GmbH  
Wallstadter Str. 59  
D-68526 Ladenburg, Germany

herewith declare under our sole responsibility, that the product series

### DCS 880 Converter Module

to which this declaration relates, do not contain substances which are restricted by Directive 2011/65/EU on the Restriction of the Use of Certain Hazardous Substances in EEE (RoHS II).

This declaration is given based on and subject to declarations of RoHS II conformity received by ABB Automation Products GmbH from its component suppliers. ABB Automation Products GmbH shall not assume any liability whatsoever for RoHS II non-compliance of the product as a result of or in connection with any faulty or misleading declaration of RoHS II conformity issued to ABB Automation Products GmbH by a supplier.

The product referred in this Declaration of Conformity fulfil the relevant provisions of other European Union Directives which are notified in Single EU Declaration of Conformity, see 3ADW00484.

Year of CE-marking: 2016

Ladenburg, 21.10.2016

  
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Wallstadter Str.59, D-68526 Ladenburg

This declaration does not express any assurance of characteristics.  
Installation and safety instructions mentioned in our installation manual must be obeyed.  
The conformity was tested in a typical configuration.



## Declaration of Conformity

( DIRECTIVE 2014/35/EU [Low Voltage Directive] )  
( DIRECTIVE 2014/30/EU [EMC Directive] )

Document code: 3ADW000478R0101

We, ABB Automation Products GmbH  
Wallstadter Str. 59  
D-68526 Ladenburg, Germany

herewith declare under our sole responsibility, that the product series

### DCS 880 Converter Module

to which this declaration relates, is a BDM / CDM according EN 61800-1:1998 [IEC 61800-1:1997].

It is in conformity with the Low Voltage Directive (LVD) 2014/35/EU and the EMC Directive (EMCD) 2014/30/EU, provided that the equipment is selected, installed and used according our instructions.

Following European standards have been applied:

- EN 61800-5-1:2007 [IEC 61800-5-1:2007]  
*Adjustable speed electrical power drive systems –  
Part 5-1: Safety requirements – Electrical, thermal and energy*
- EN 61800-3:2004 + A1:2012 [IEC 61800-3:2004 + A1:2011]  
*Adjustable speed electrical power drive systems –  
Part 3: EMC requirements and specific test methods*

Year of CE-marking: 2016

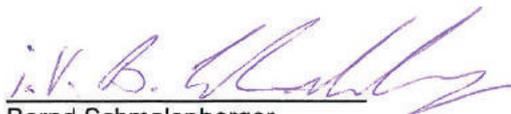
This declaration is based on Technical Construction File, code 3ADT061070. It is provided, that instructions for installation, operation and maintenance are according the product documentation.

The product referred in this Declaration of Conformity fulfil the relevant provisions of other European Union Directives which are notified in Single EU Declaration of Conformity, see 3ADW000484.

Ladenburg, 21.10.2016

  
\_\_\_\_\_  
Holger Kröhler

Local Division IMS Manager  
Wallstadter Str.59, D-68526 Ladenburg

  
\_\_\_\_\_  
Bernd Schmalenberger

Local Operation Manager  
Wallstadter Str.59, D-68526 Ladenburg

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The conformity was tested in a typical configuration.

## DCS Familie



### DCS550-S modules The compact drive for machinery application

20 ... 1,000 A<sub>DC</sub>  
0 ... 610 V<sub>DC</sub>  
230 ... 525 V<sub>AC</sub>  
IP00

- Compact
- Robust design
- Adaptive and winder program
- High field exciter current



### DCS880 modules For safe productivity

20 ... 5,200 A<sub>DC</sub>  
0 ... 1,600 V<sub>DC</sub>  
230 ... 1,000 V<sub>AC</sub>  
IP00

- Safe torque off (STO) built in as standard
- Compact and robust
- Single drives, 20 A to 5,200 A, up to 1,600 V<sub>DC</sub>
- IEC 61131 programmable
- Intuitive control panel and PC tool with USB connection and start up assistant
- Wide range of options to serve any DC motor application



### DCS800-A enclosed converters Complete drive solutions

20 ... 20,000 A<sub>DC</sub>  
0 ... 1,500 V<sub>DC</sub>  
230 ... 1,200 V<sub>AC</sub>  
IP21 – IP54

- Individually adaptable to customer requirements
- User-defined accessories like external PLC or automation systems can be included
- High power solutions in 6- and 12-pulse up to 20,000 A, 1,500 V
- In accordance to usual standards
- Individually factory load tested
- Detailed documentation



### DCT880 modules Thyristor controller

16 ... 4,200 A<sub>DC</sub>  
110 ... 190 V<sub>DC</sub>  
IP00

- Precise power control in industrial heating applications
- Two or three phase devices
- Power optimizer for peak load reduction
- Built on ABB's all-compatible drives architecture
- Intuitive control panel and PC tool with USB connection and start up assistant
- Application control programs and drive application programming with IEC 61131-3 programming

# ABB

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